



IceCube Moon Shadow

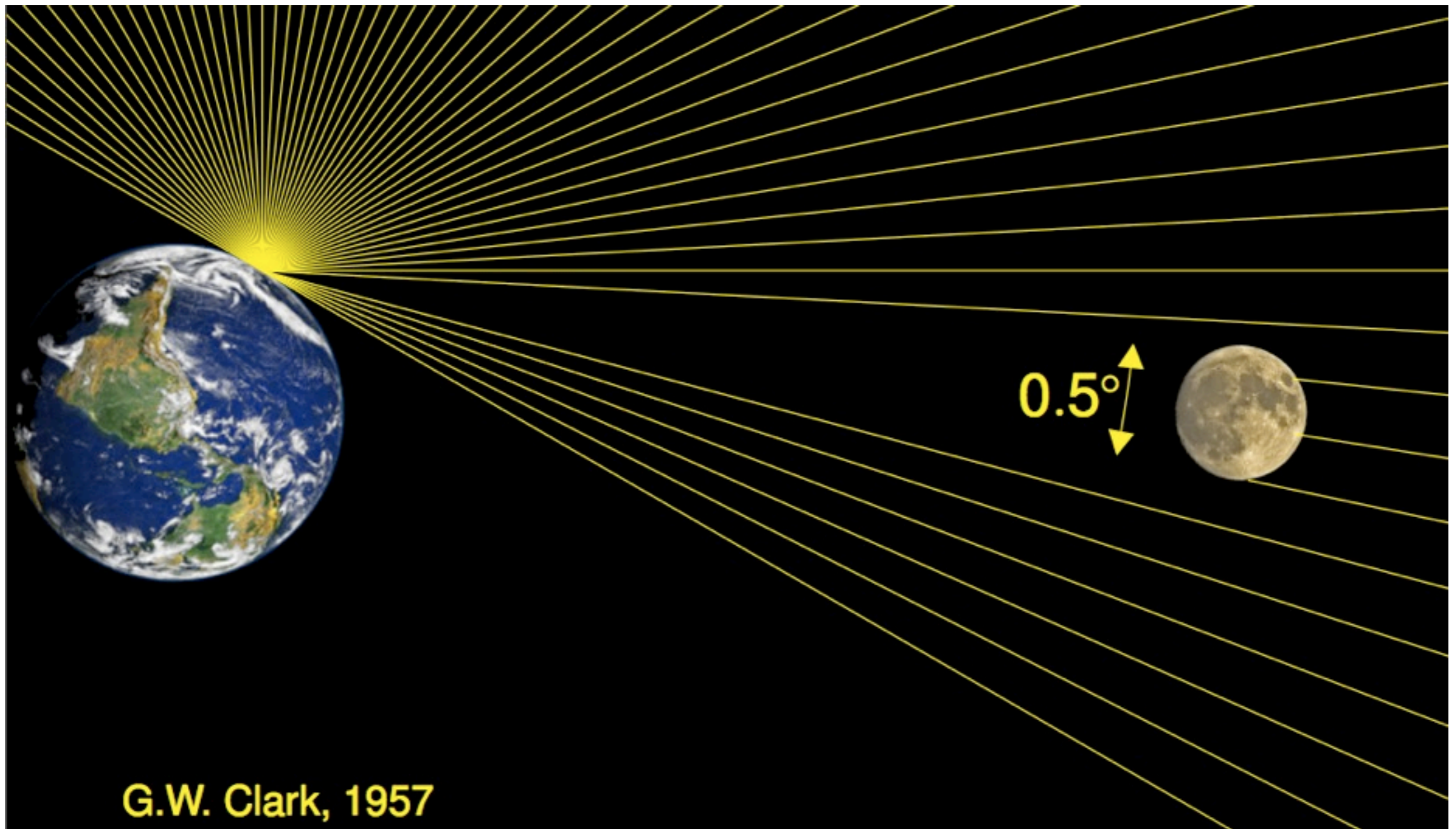
Laura Gladstone
University of Wisconsin, Madison

Moriond Electroweak Session
20 March 2011



Shadow is a known signal

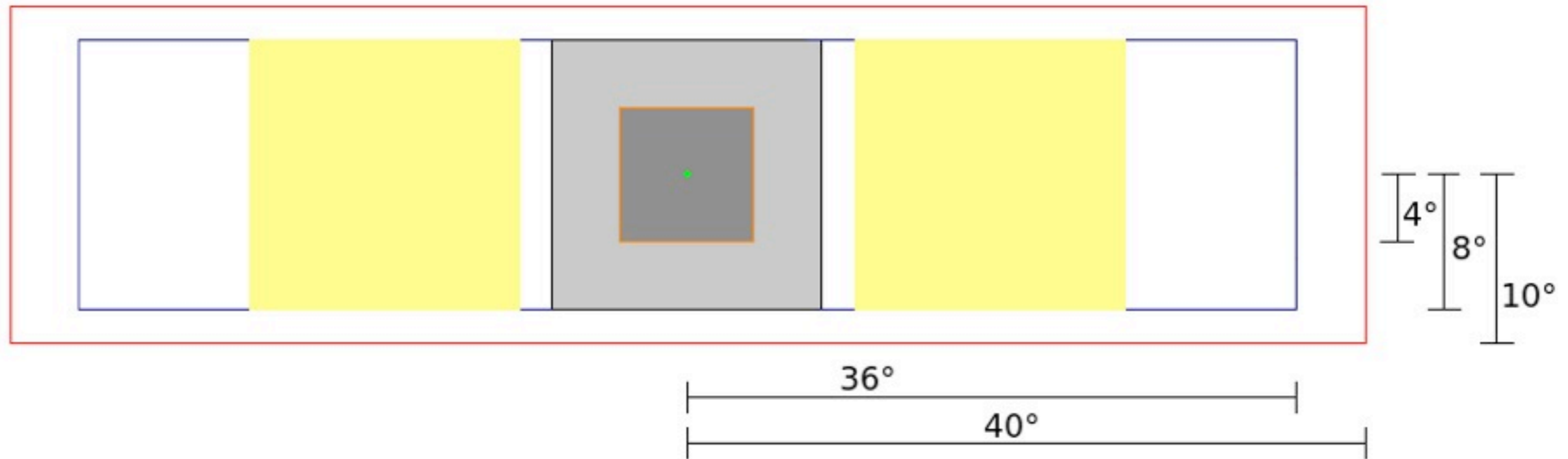
2



- End-to-end check of systematics and pointing

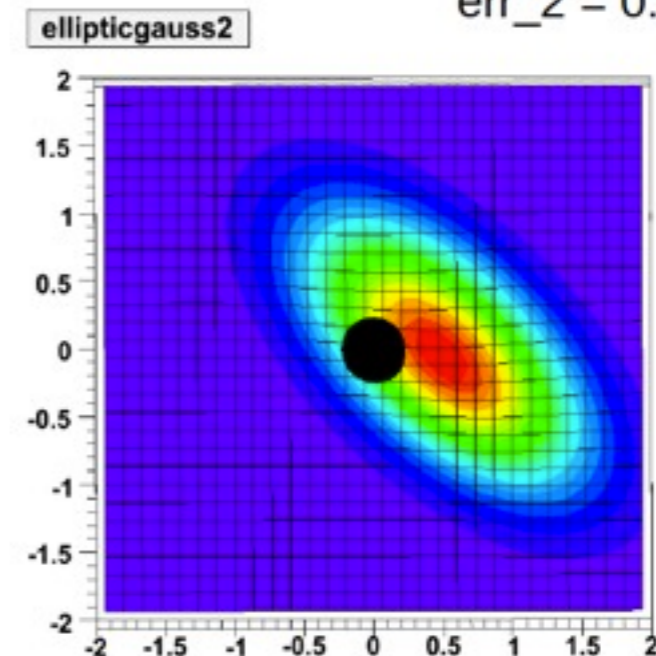
Data Sample

3



- Use events from a window around the Moon
- Angular resolution is comparable to the size of the Moon

one example event: $\text{err}_1 = 0.4^\circ$
 $\text{err}_2 = 0.8^\circ$

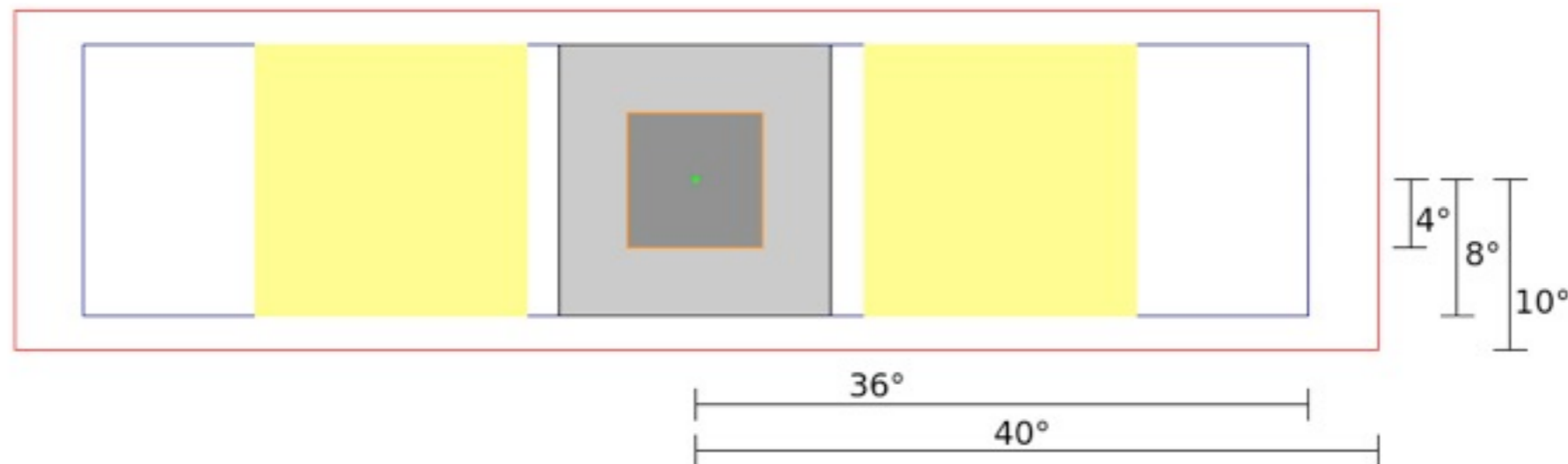


Likelihood Approach

4

$$L(\vec{x}_s, n_s) = \sum_i^N \log \left(\frac{n_s}{N} S_i + \left(1 - \frac{n_s}{N} B_i\right) \right)$$

- Use central signal region and off-source background region
- At each point, vary the number of events blocked by the Moon, n_s
- Maximize likelihood

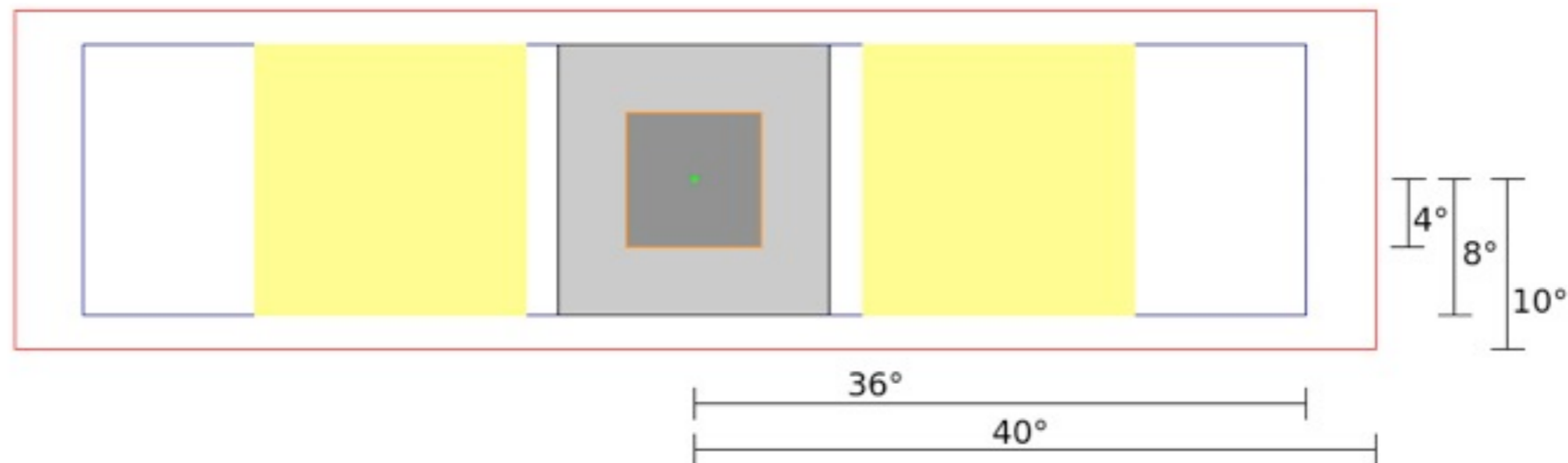


Likelihood Approach

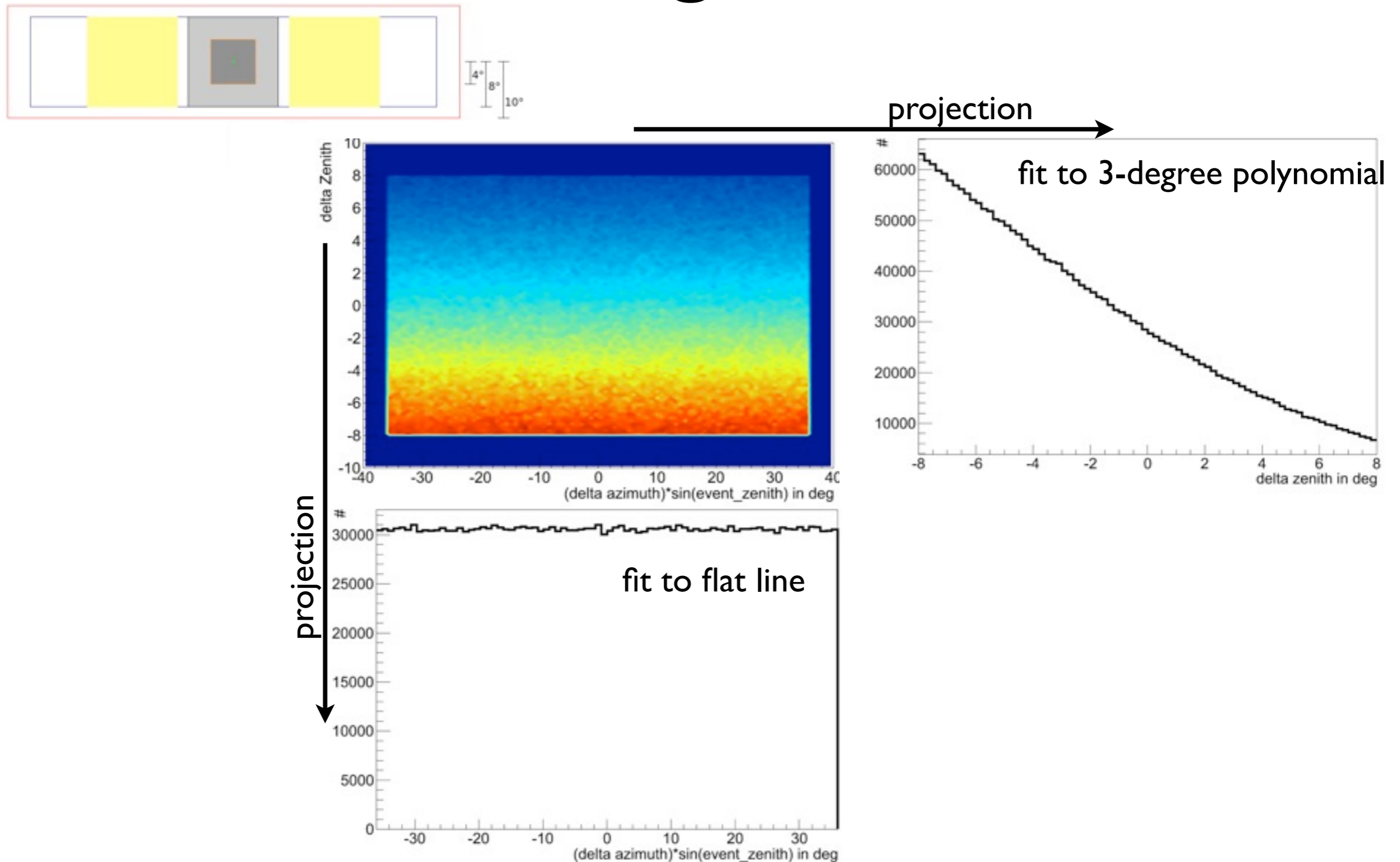
4

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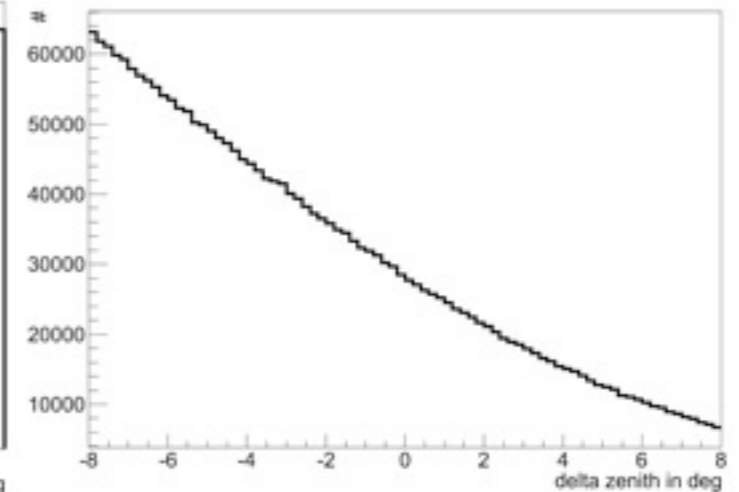
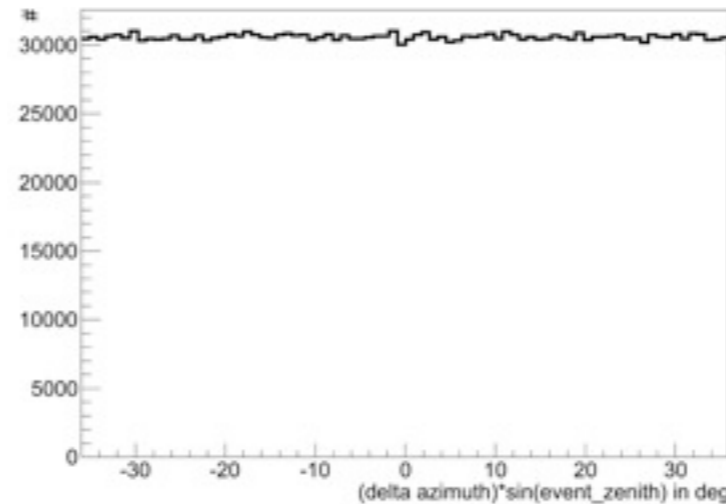
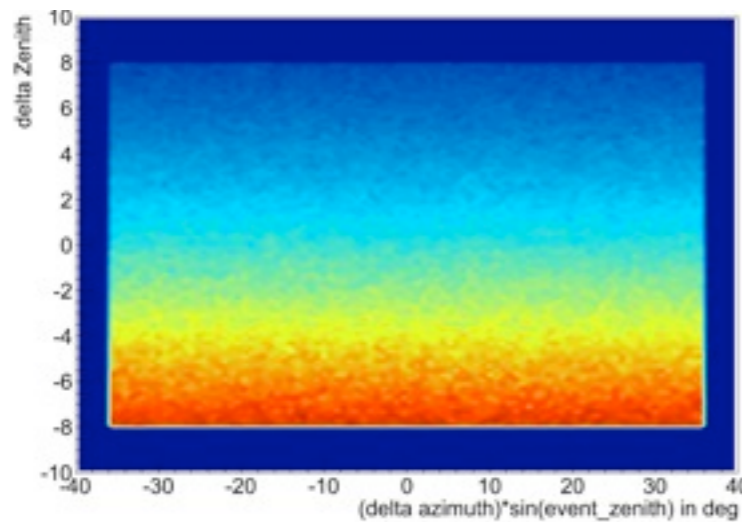


Likelihood: background function ⁵



How steady is background

6

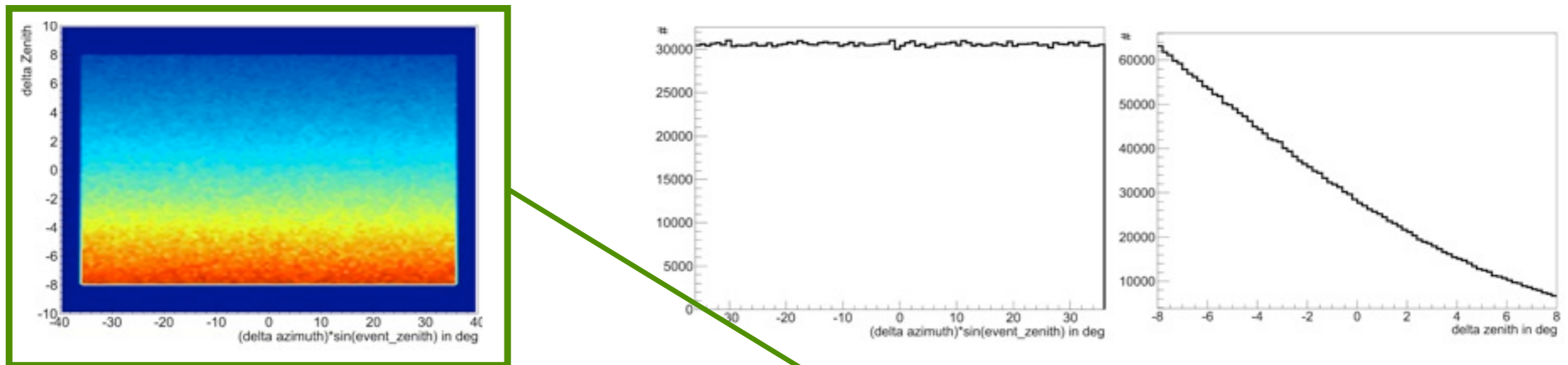


$$L(\vec{x}_s, n_s) = \sum_i^N \log \left(\frac{n_s}{N} S_i + \left(1 - \frac{n_s}{N} B_i \right) \right)$$

Null hypothesis
fluctuations: look at
off-source region as if
it were signal

How steady is background

6

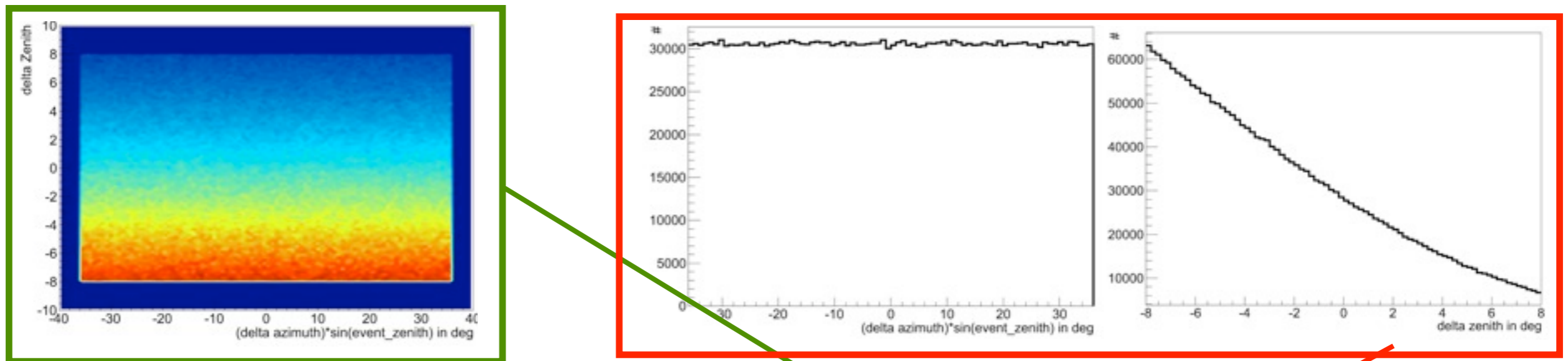


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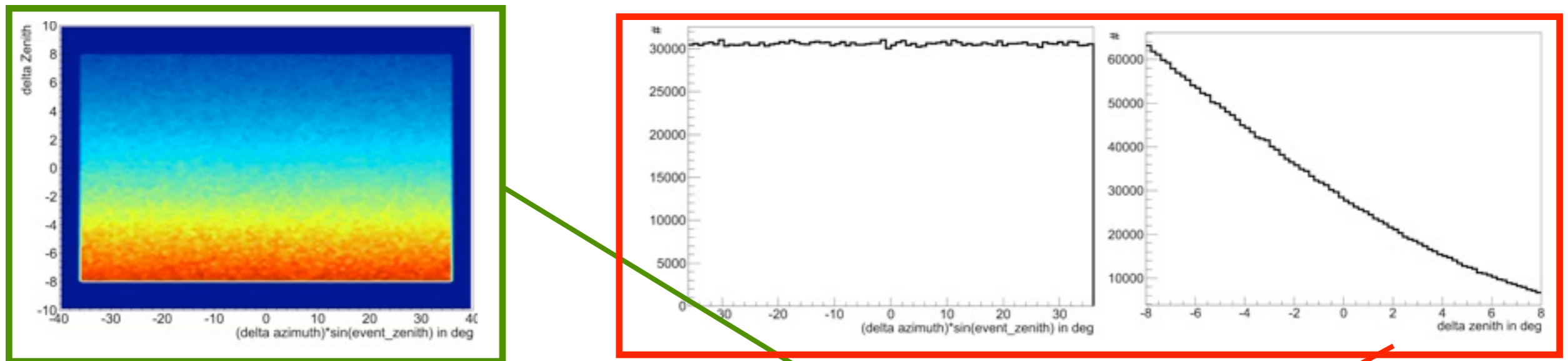


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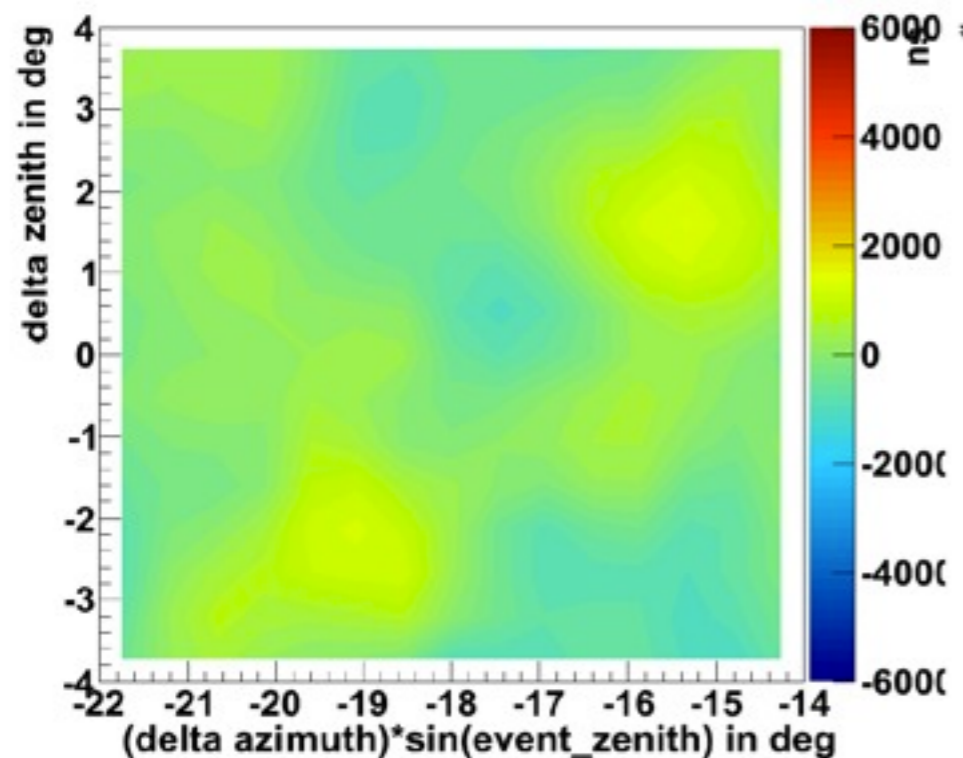
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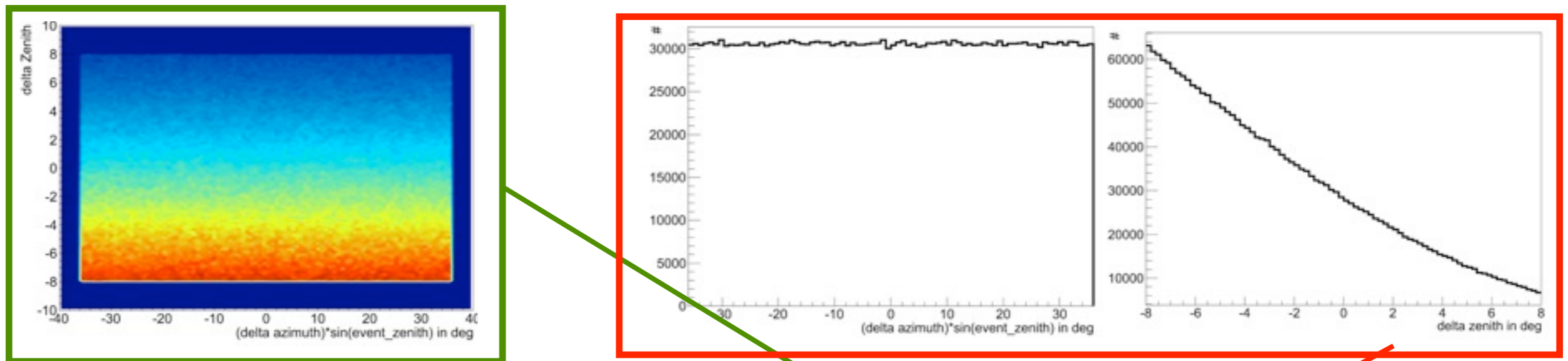
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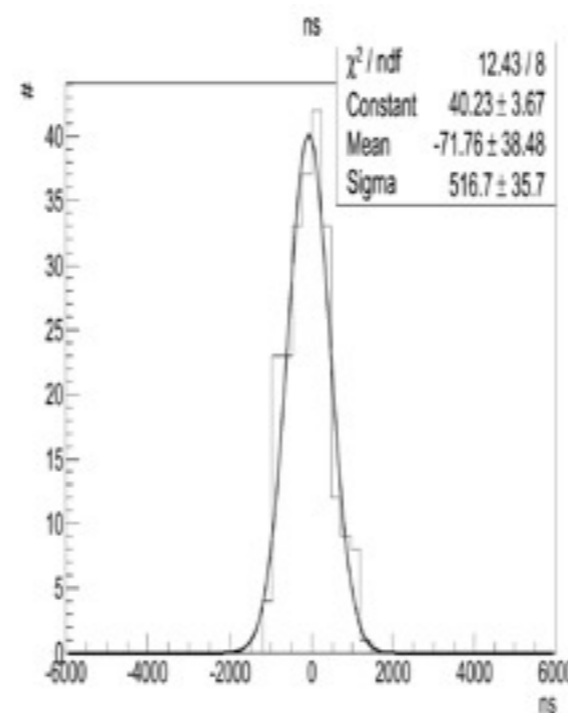
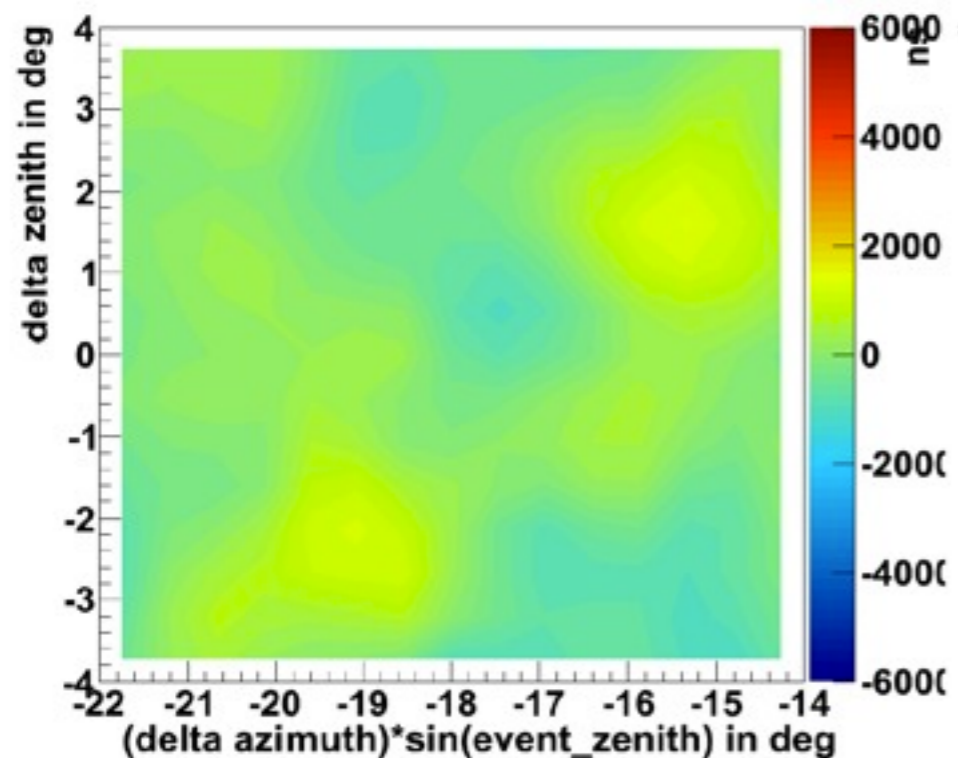
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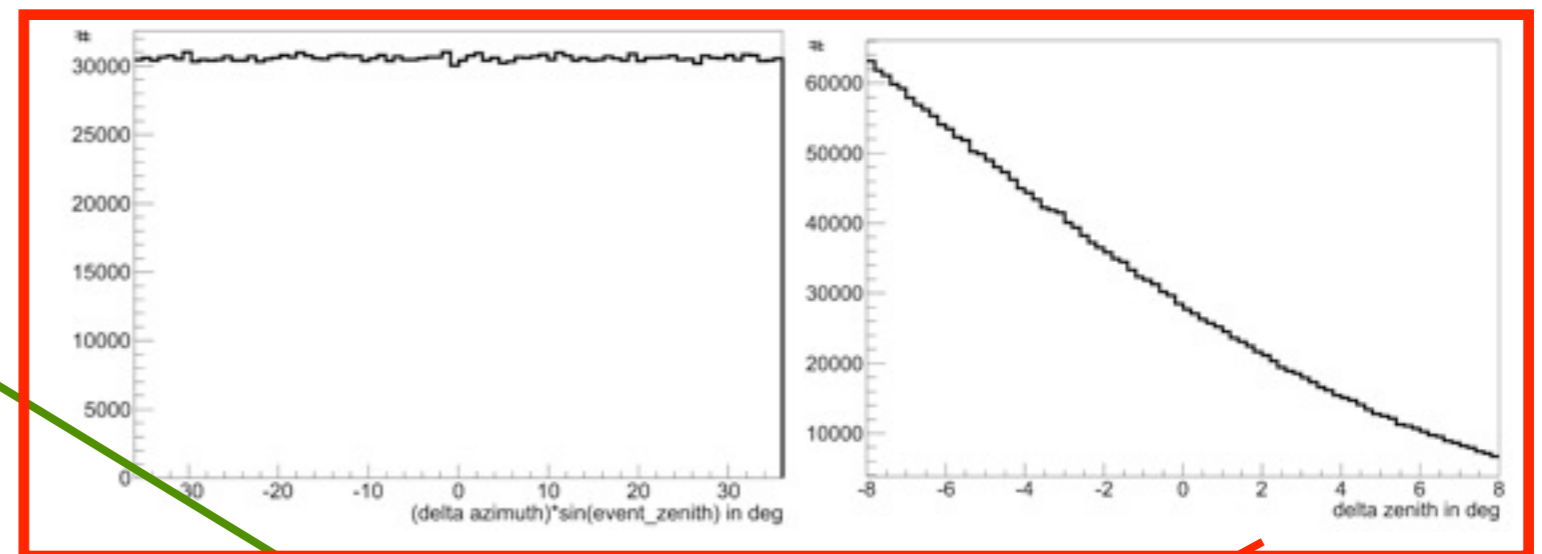
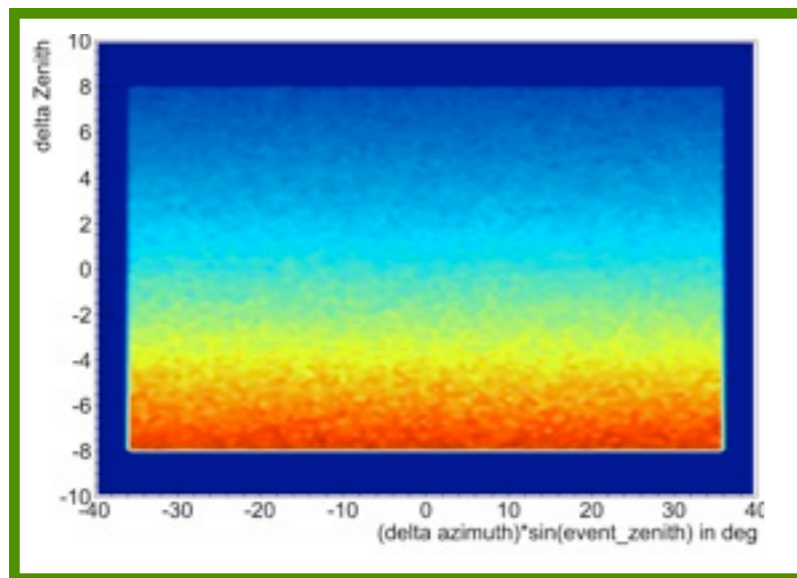
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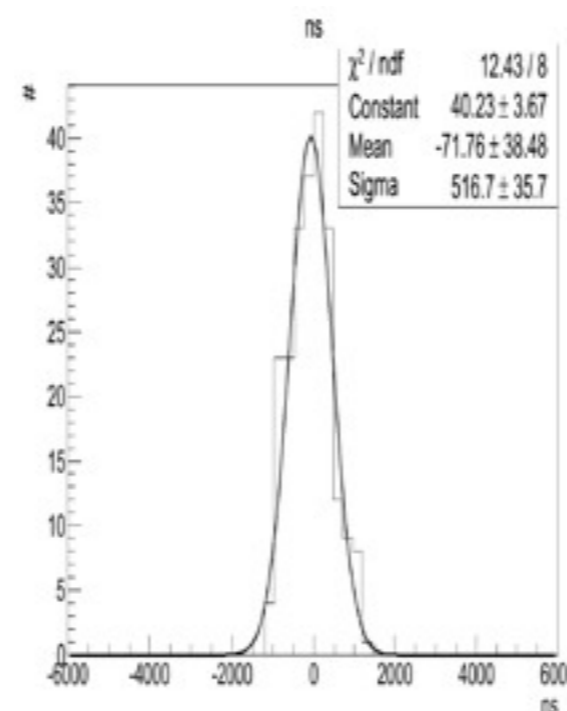
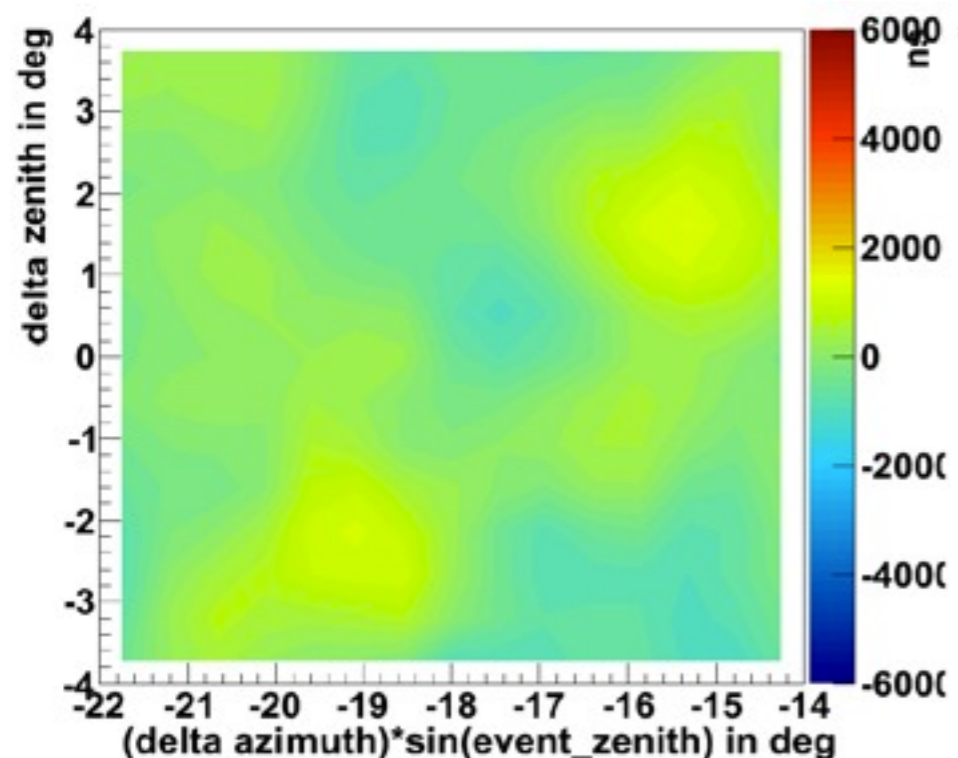
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How steady is background

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$$L(\vec{x}_s, n_s) = \sum_i^N \log \left(\frac{n_s}{N} S_i + \left(1 - \frac{n_s}{N} B_i \right) \right)$$

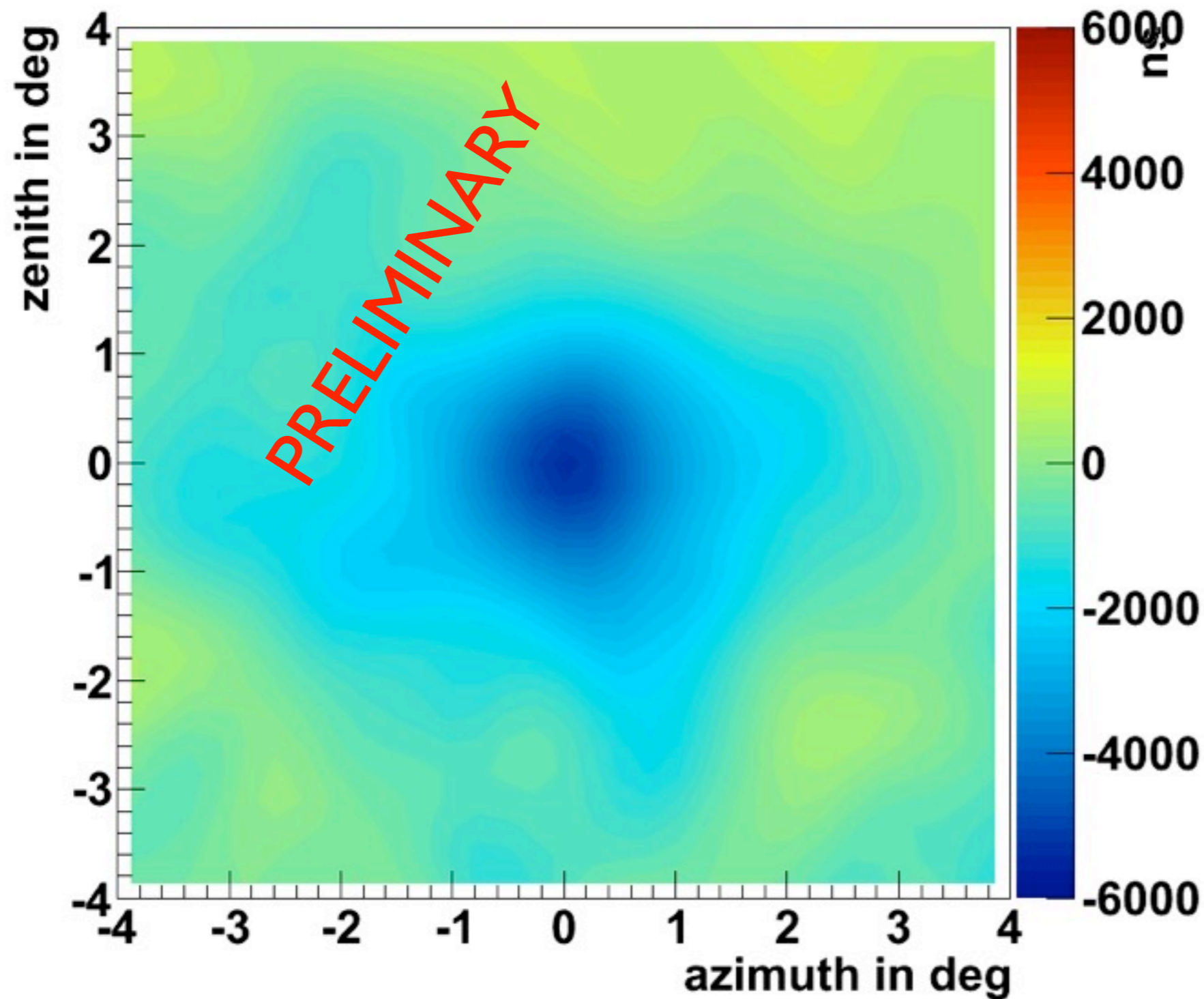


Null hypothesis
fluctuations: look at
off-source region as if
it were signal

Width = 500 events

Likelihood result PRELIMINARY

7



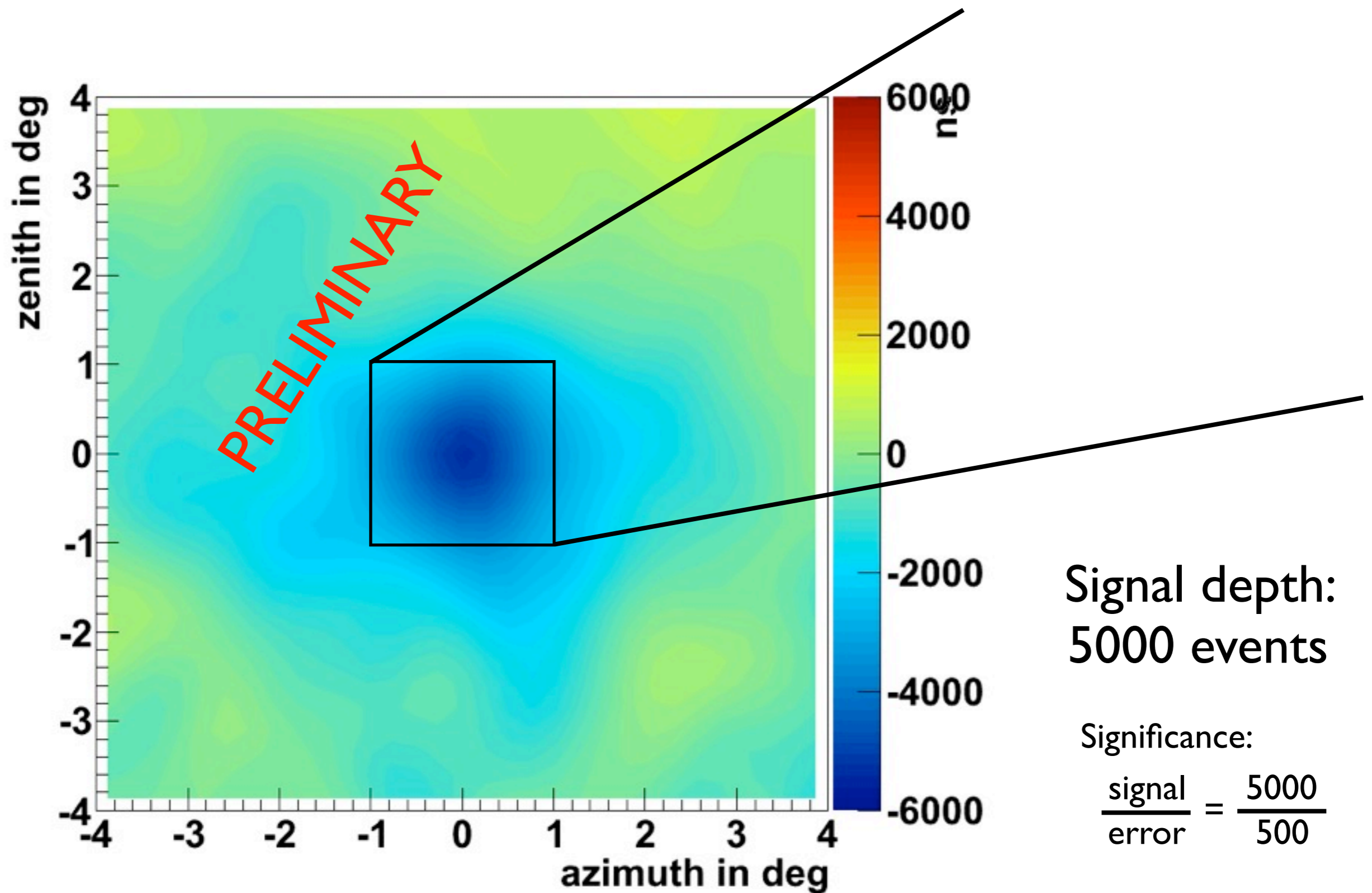
Signal depth:
5000 events

Significance:

$$\frac{\text{signal}}{\text{error}} = \frac{5000}{500}$$

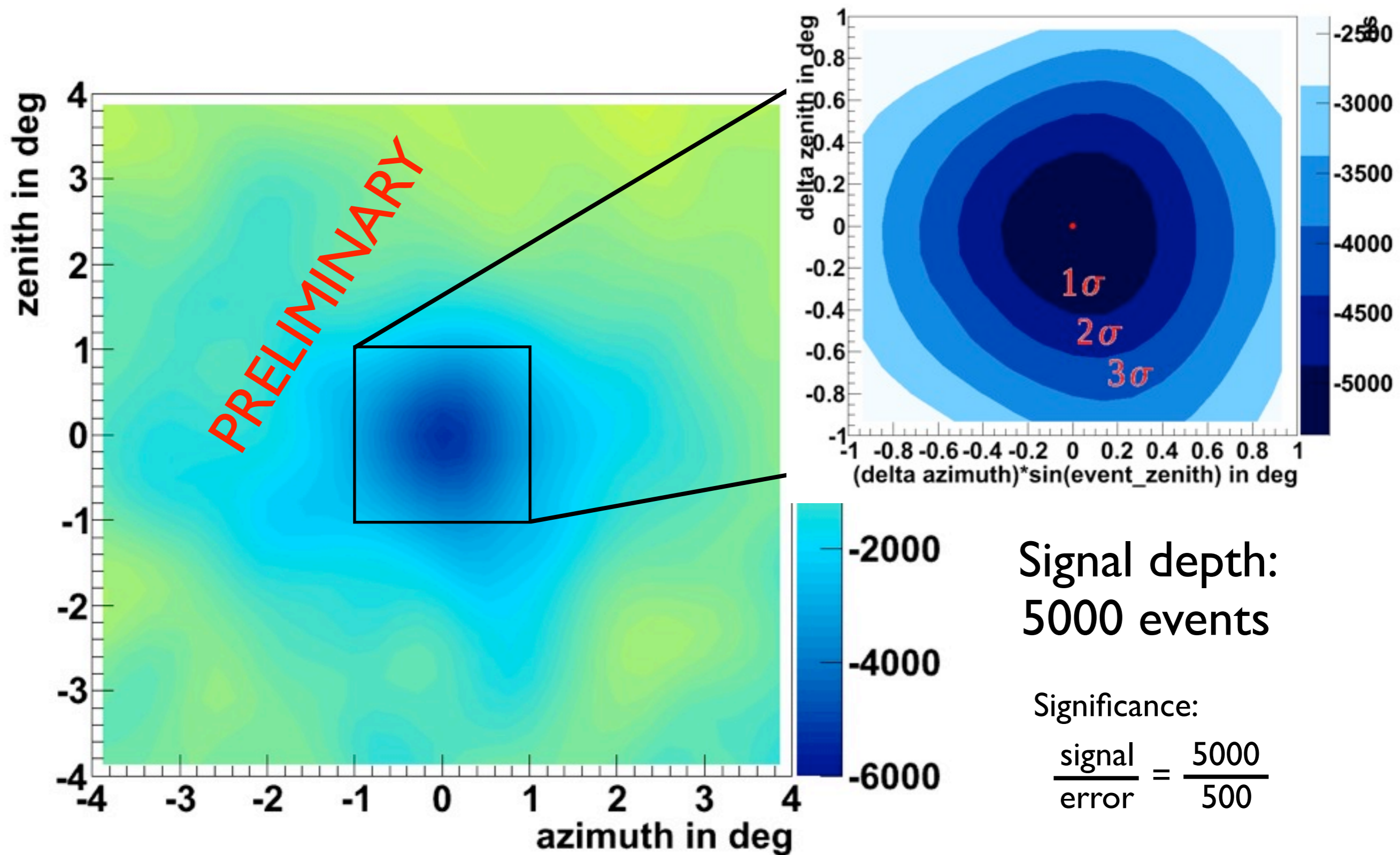
Likelihood result **PRELIMINARY**

7



Likelihood result PRELIMINARY

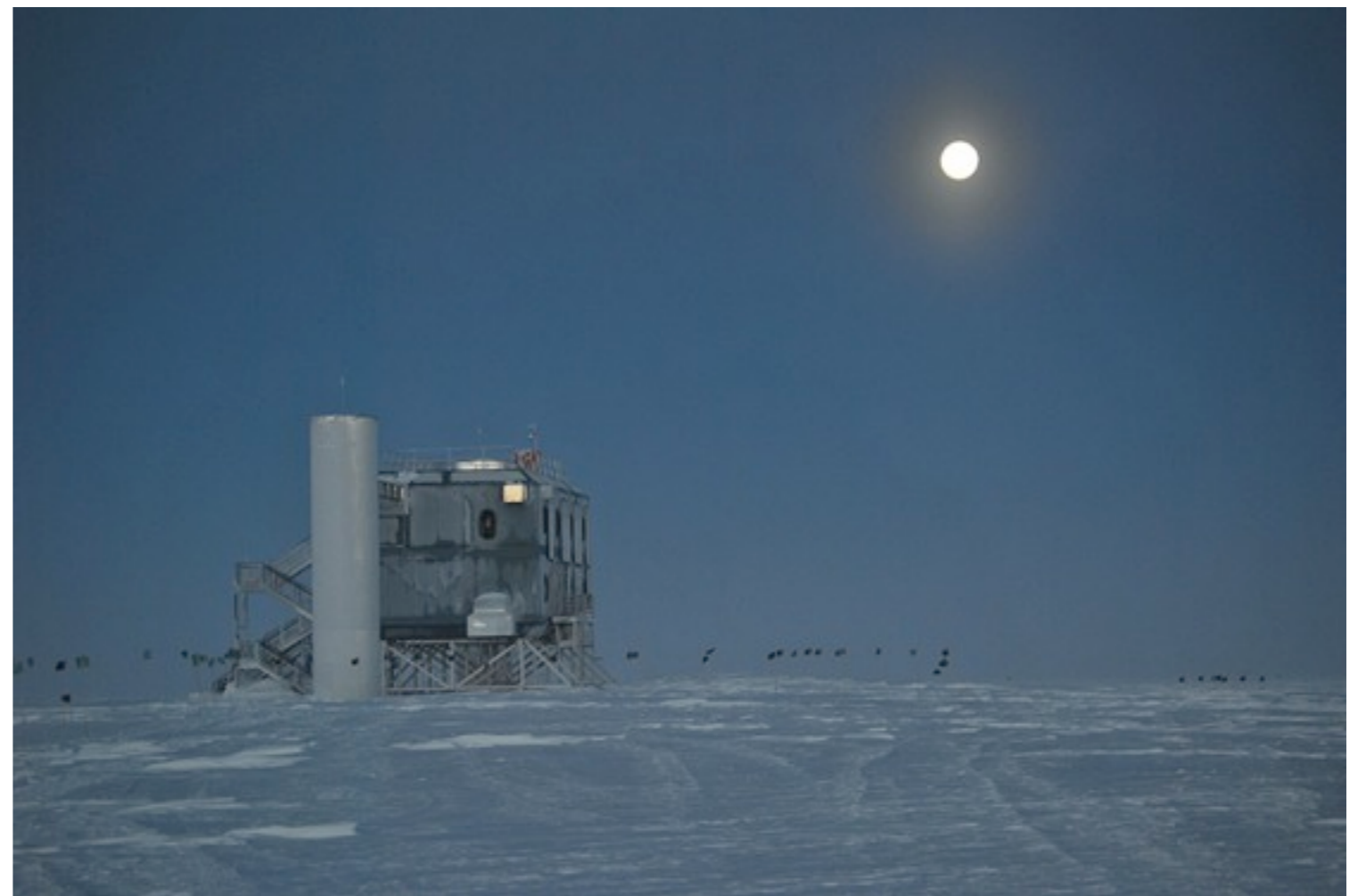
7



Conclusion:

8

- IceCube observes the Moon shadow with 10σ , confirming accurate pointing up to $\mathcal{O}(^\circ)$



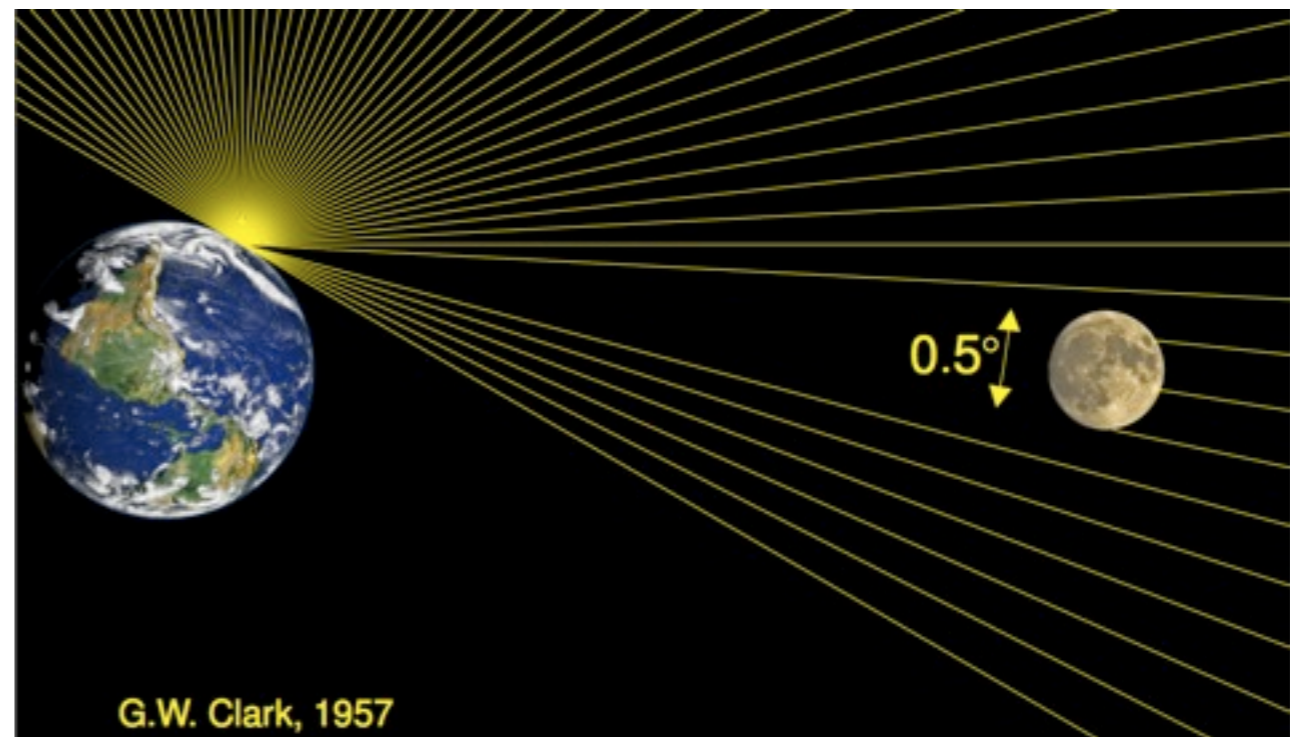
Thanks to the IceCube Moon group,
especially:

David Boersma
Jan Blumenthal
Hugo Stiebel
Marcos Santander

Uses for a known shadow

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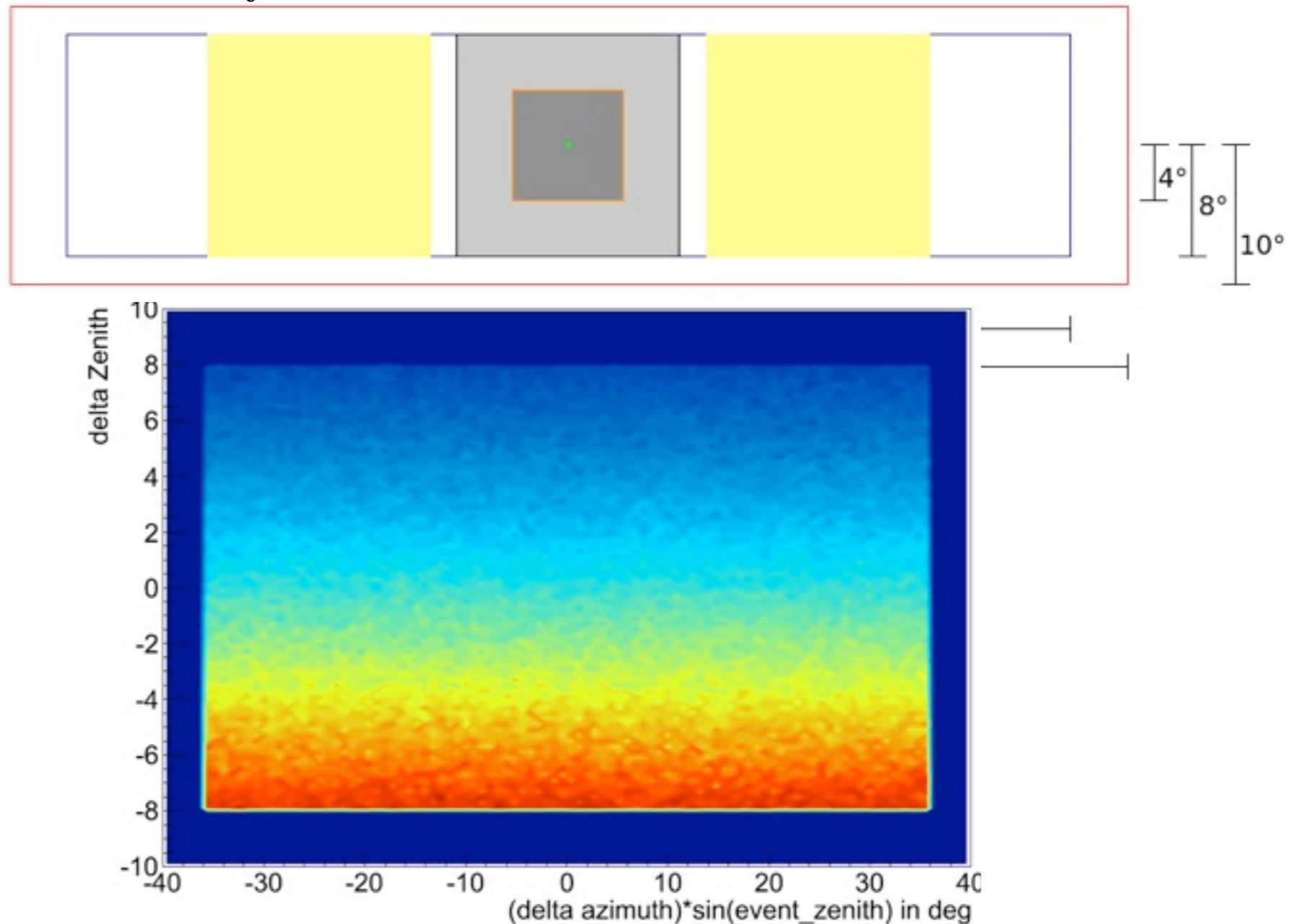
- End-to-end check of systematics and pointing
 - Monitor monthly to confirm data
- Use the shadow shape to describe the detector point spread function
- Vary fit parameters and observe the effect on shadow strength
 - confirms simulation accuracy



Likelihood: background

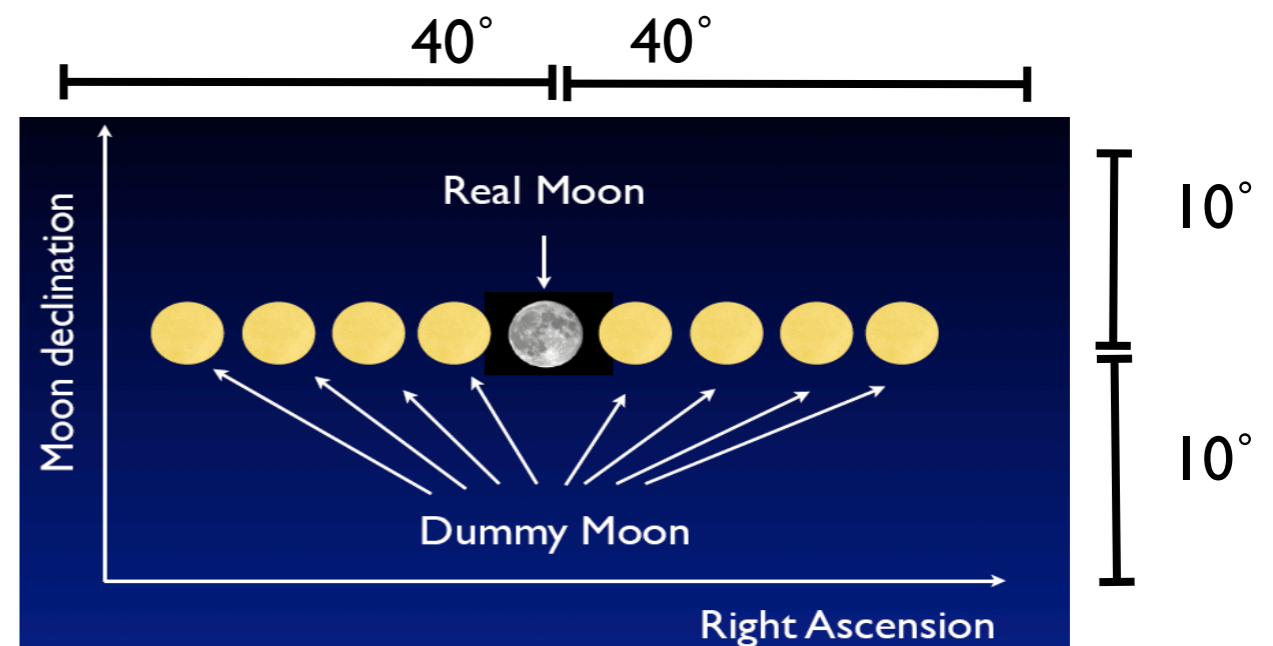
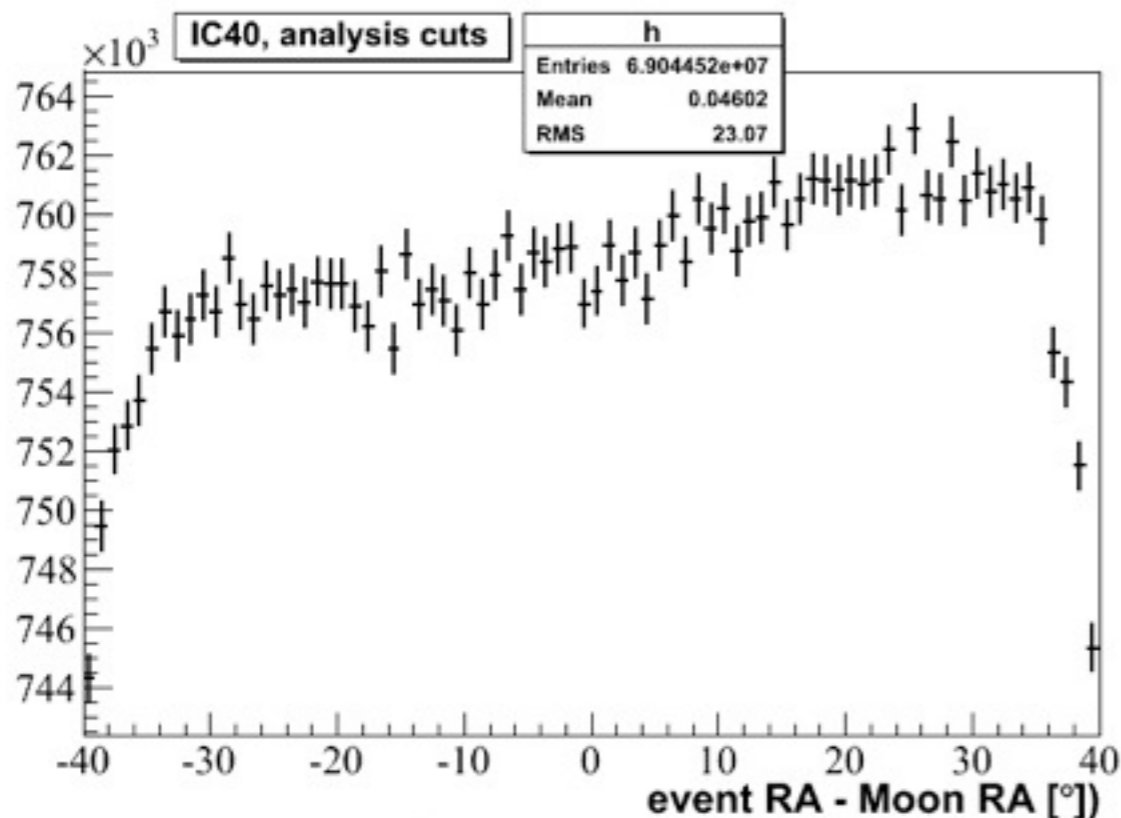
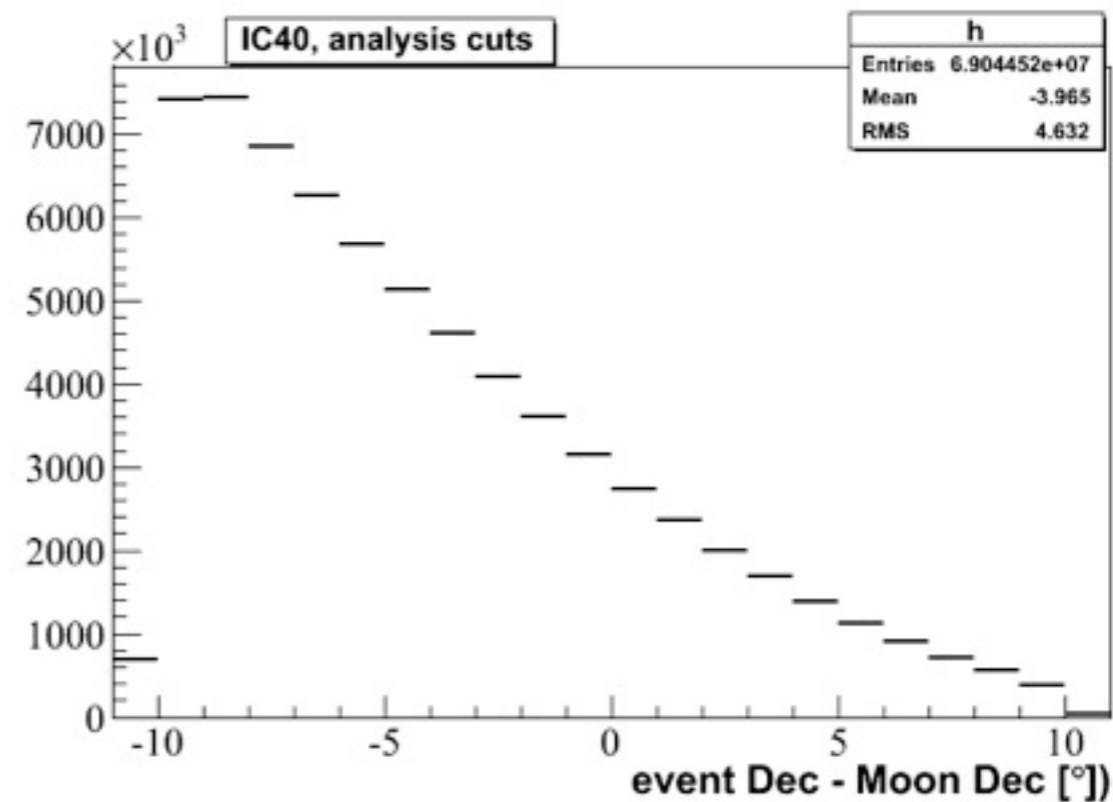
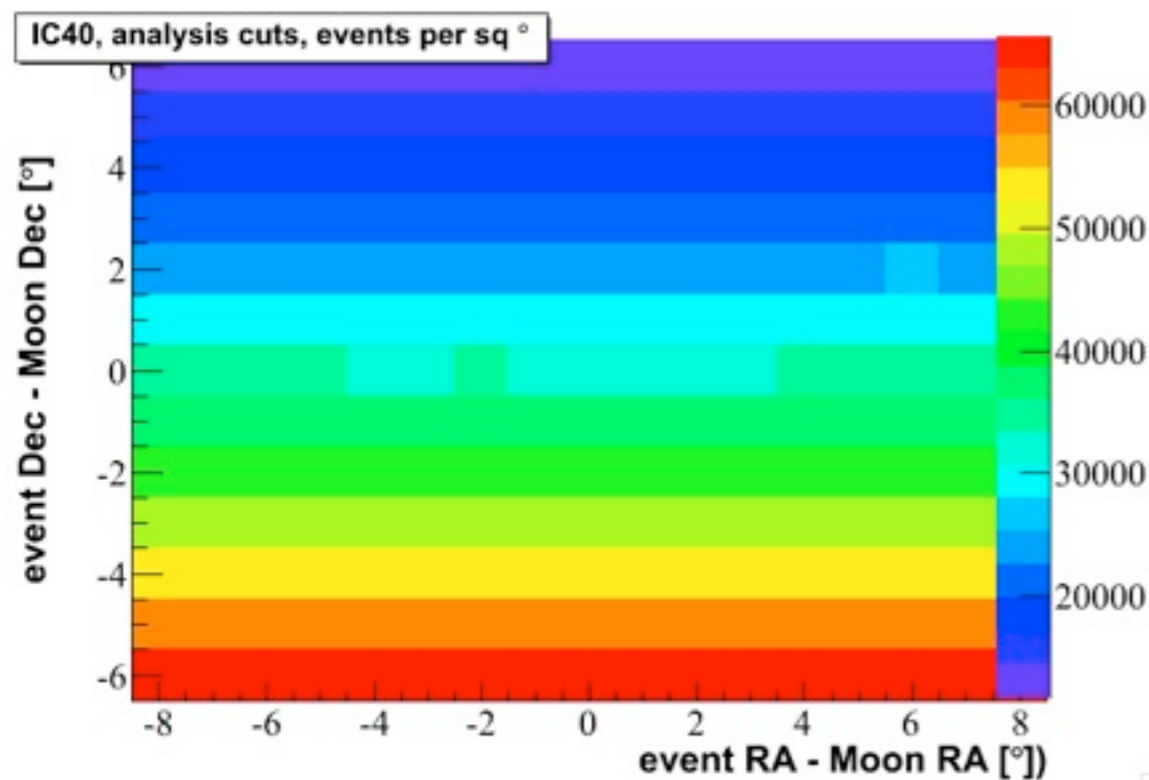
10

$$L(\vec{x}_s, n_s) = \sum_i^N \log \left(\frac{n_s}{N} S_i + \left(1 - \frac{n_s}{N}\right) B_i \right)$$



Data set

11



Data Quality Cuts

12

- Filter-level cuts:
 - (number of hit DOMs) \equiv NCh ≥ 12
 - (number of hit strings) ≥ 3
- Analysis-level cuts:
 - estimated angular error of reconstruction $\leq 1.6^\circ$
- Resulting sample:
 - 69M events, 53% efficiency from filter
 - median angular resolution: 1.27°
- Search Bin Size: 0.8°

Search bin size optimization

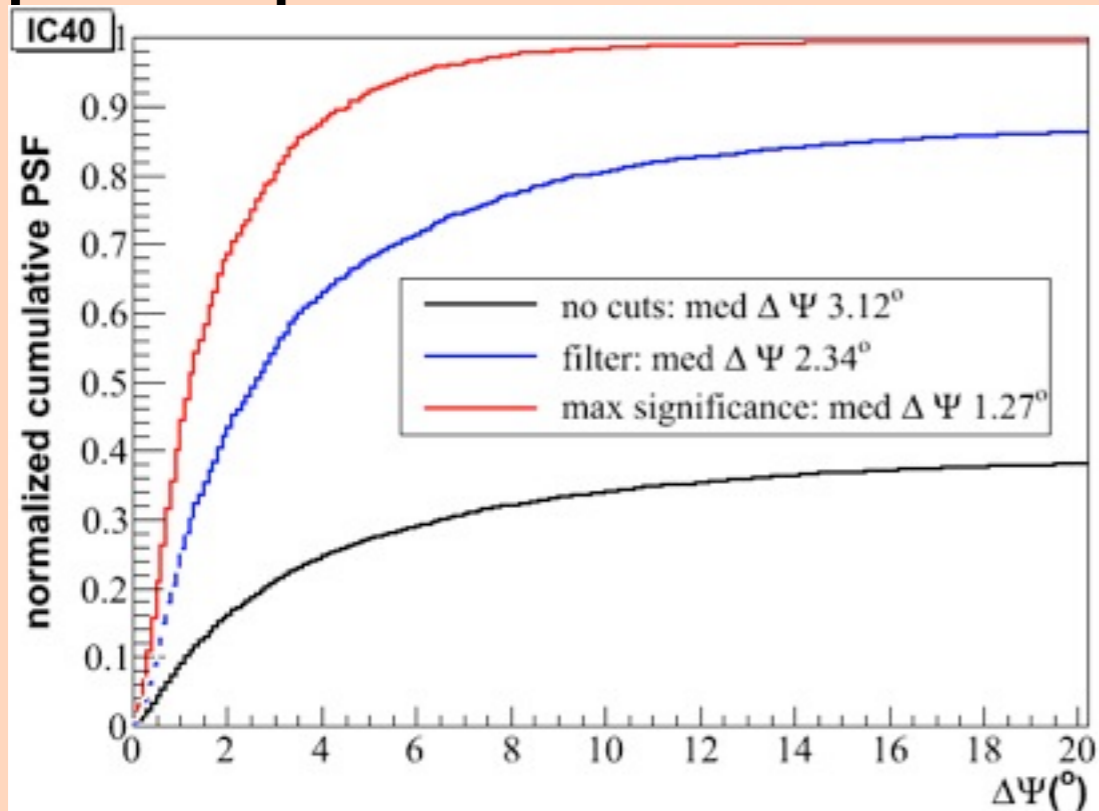
13

$$\text{significance} \sim \frac{N_{sig}}{\sqrt{N_{bkgd}}}$$

Search bin size optimization

13

Signal: use simulated point spread function

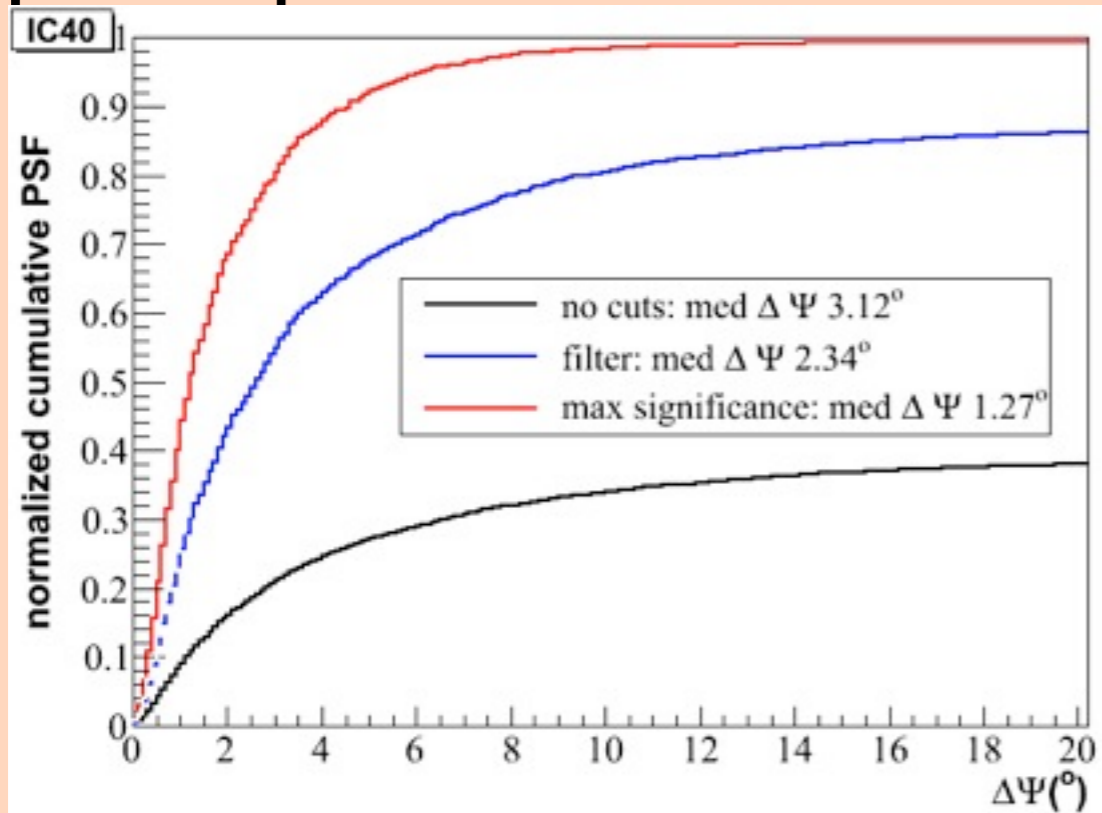


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Search bin size optimization

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Signal: use simulated point spread function



$$\text{significance} \sim \frac{N_{sig}}{\sqrt{N_{bgd}}}$$

Background: scales with area

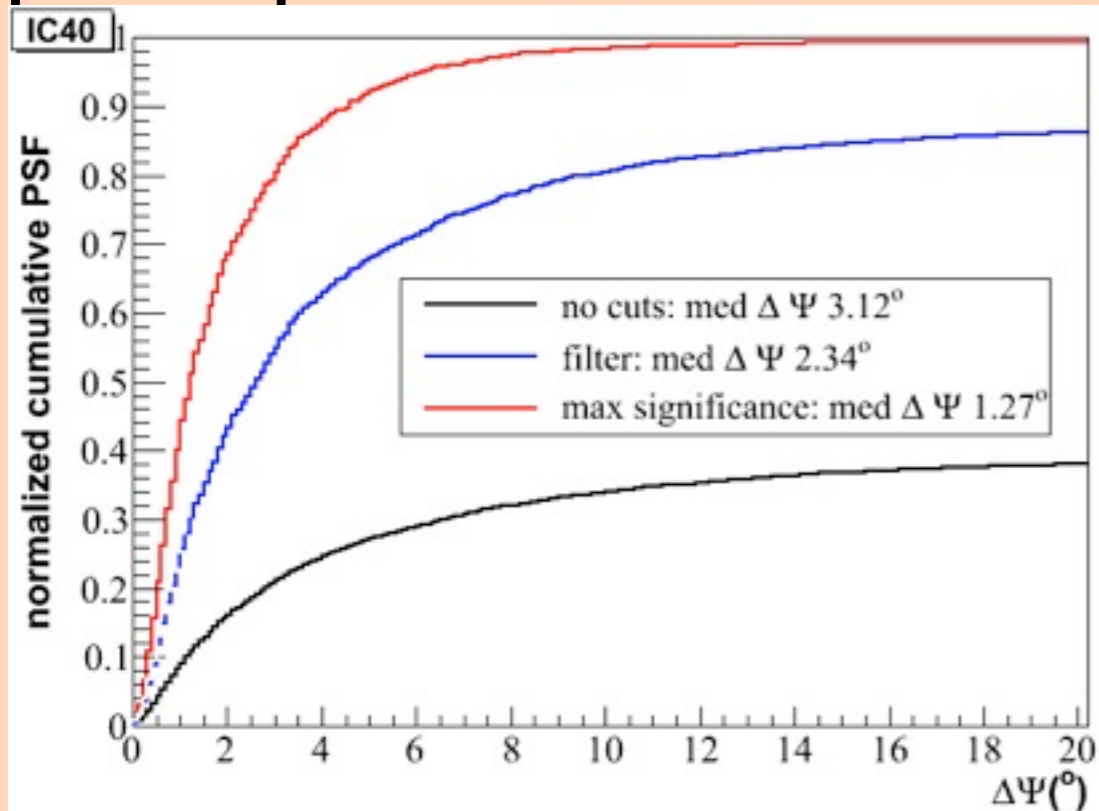
$$N_{bgd} \propto \text{Area} \propto \pi r^2$$

$$\sqrt{N_{bgd}} \propto r$$

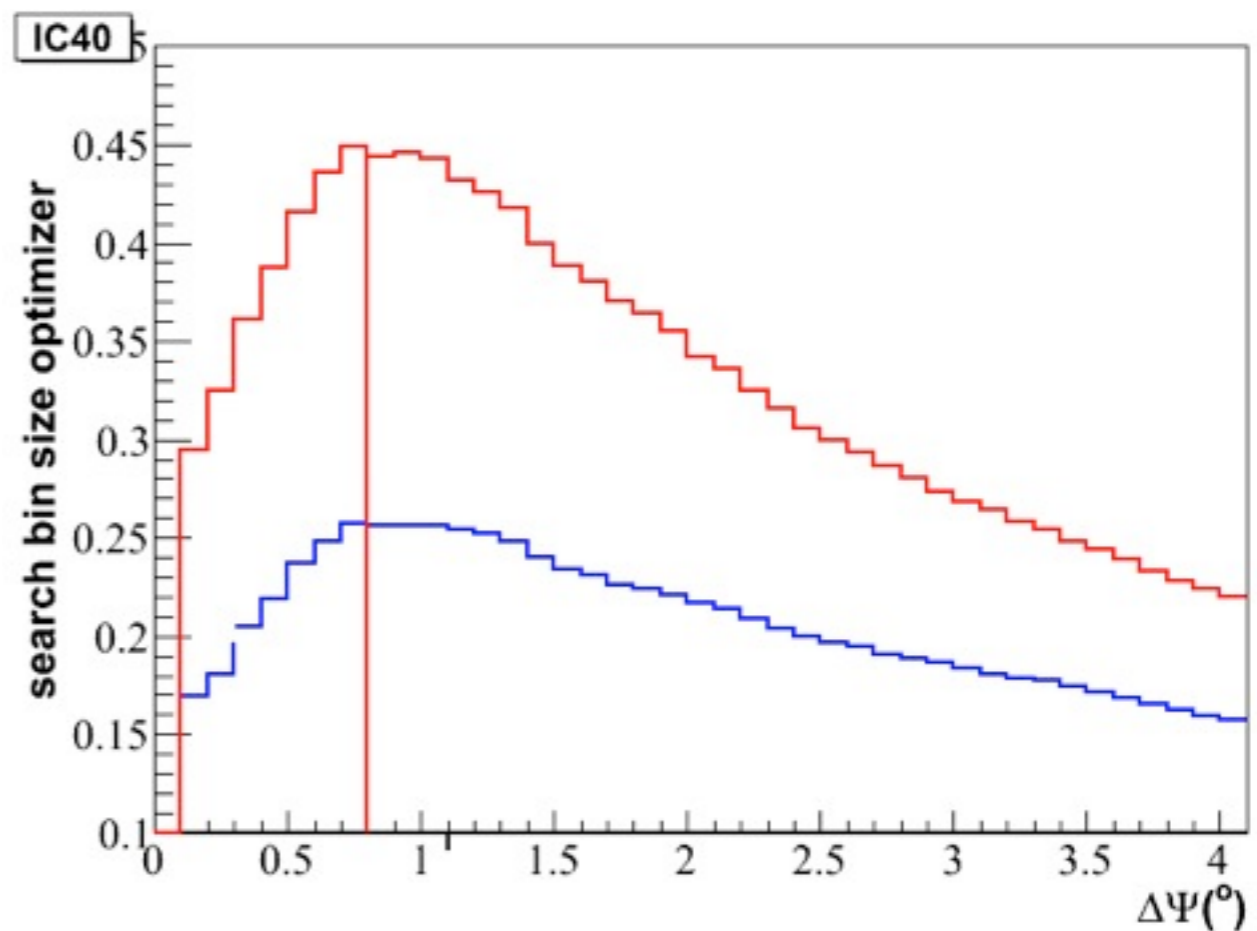
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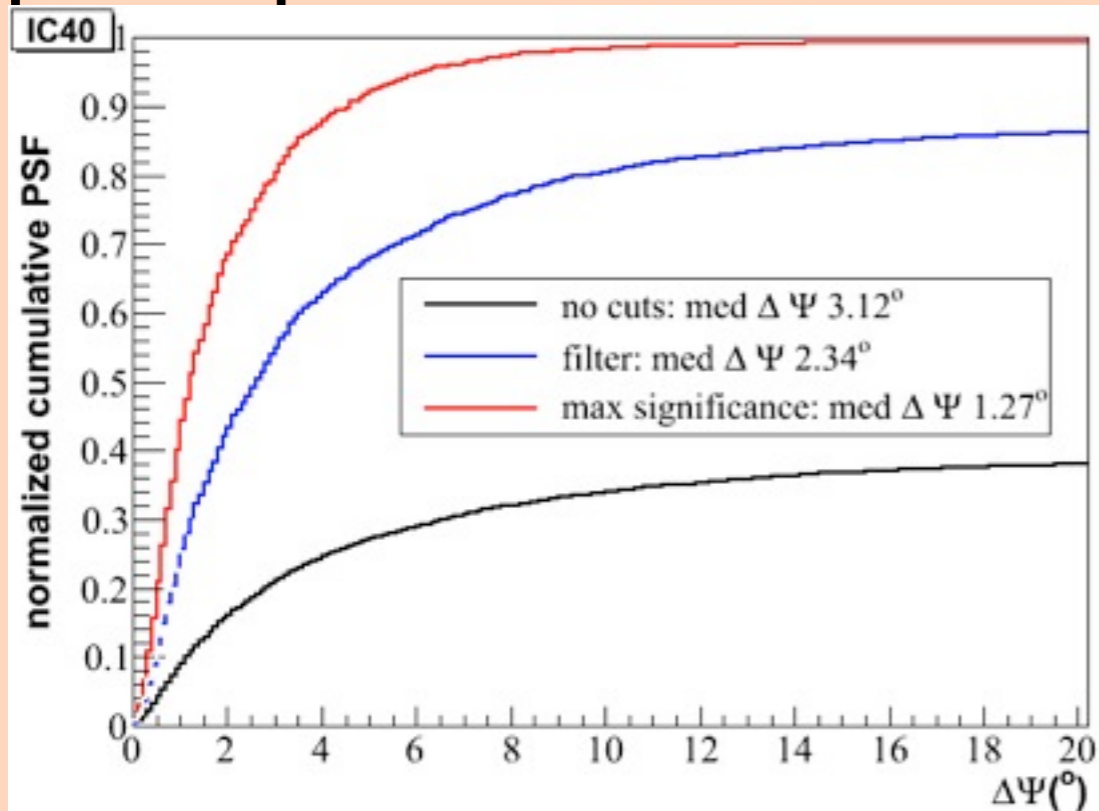
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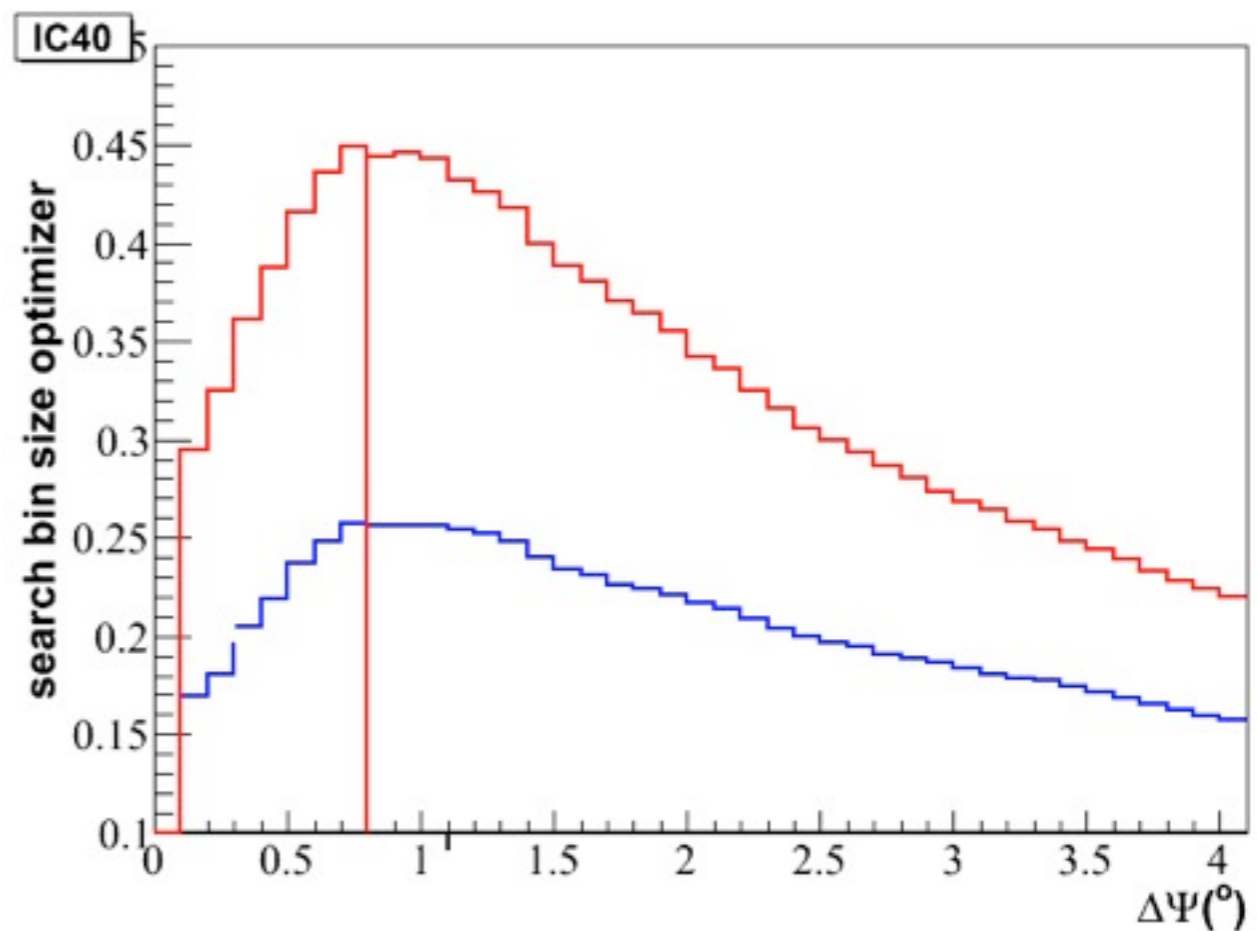
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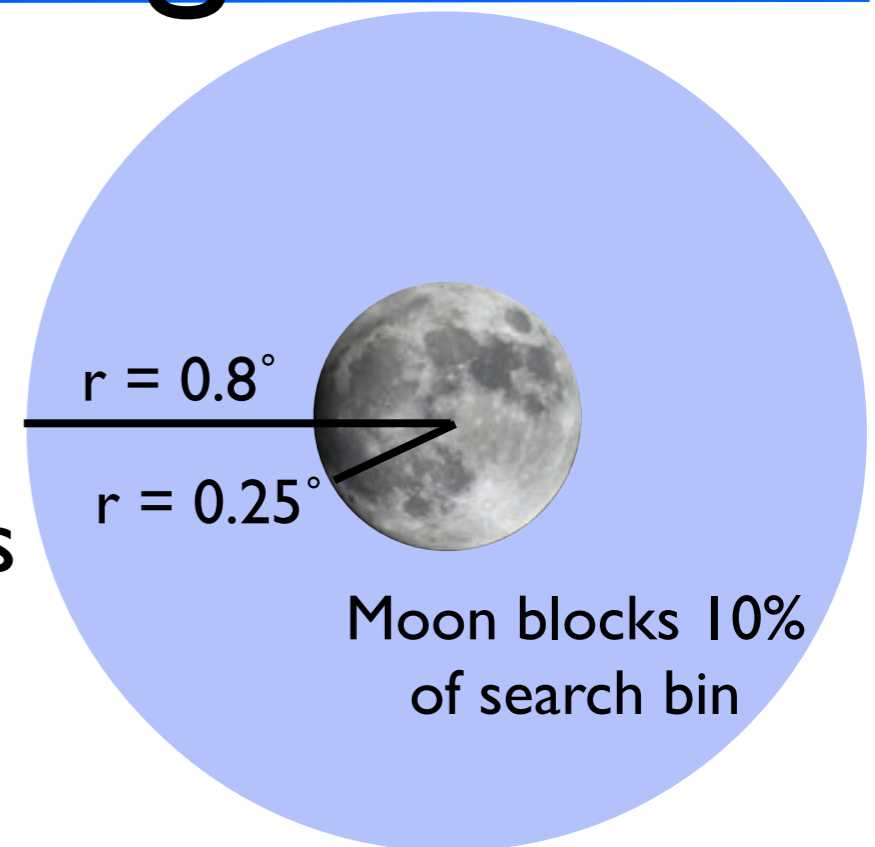
$$\sqrt{N_{bkgd}} \propto r$$

Expect best result with search bin of 0.8°

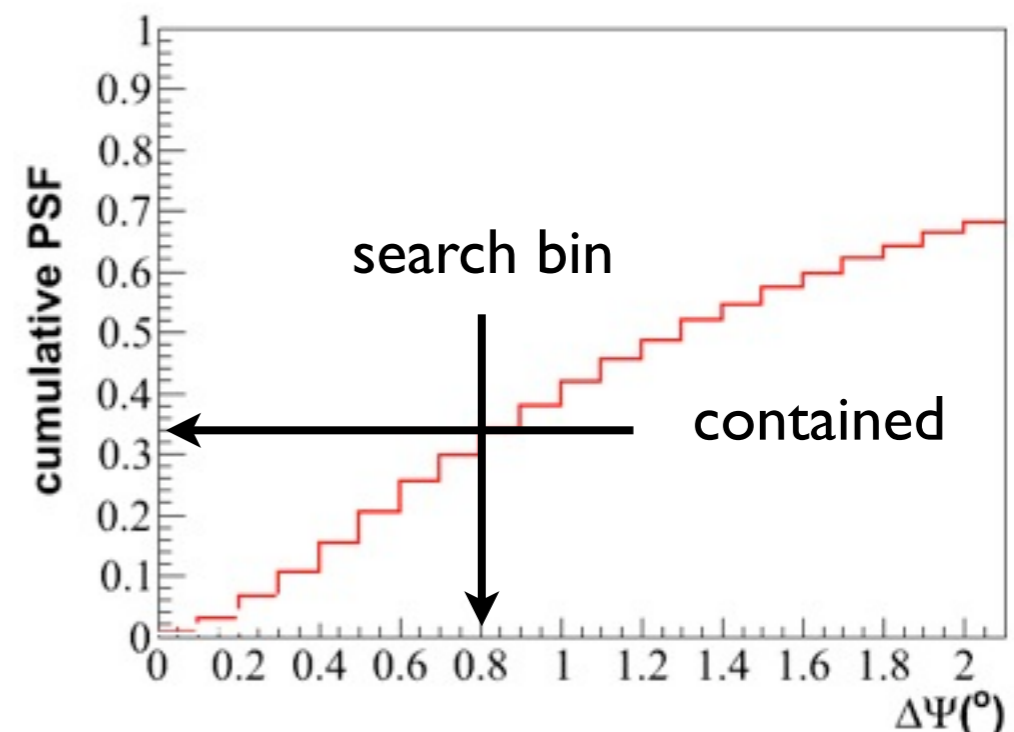
Back-of-the-Envelope Significance

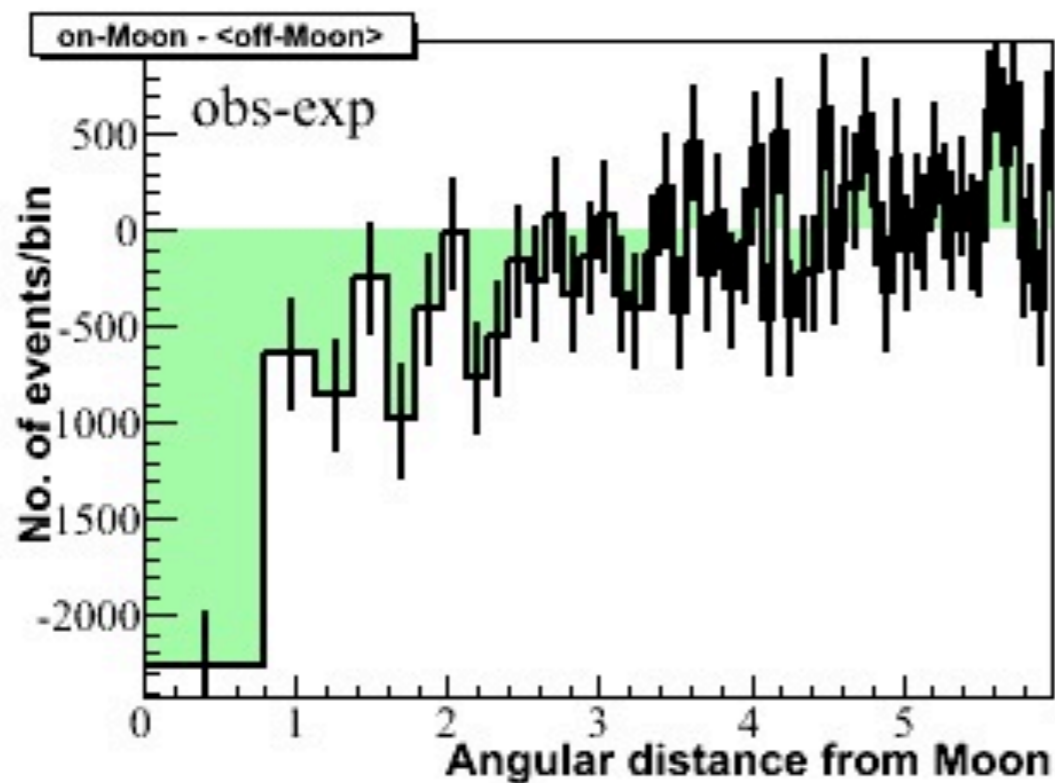
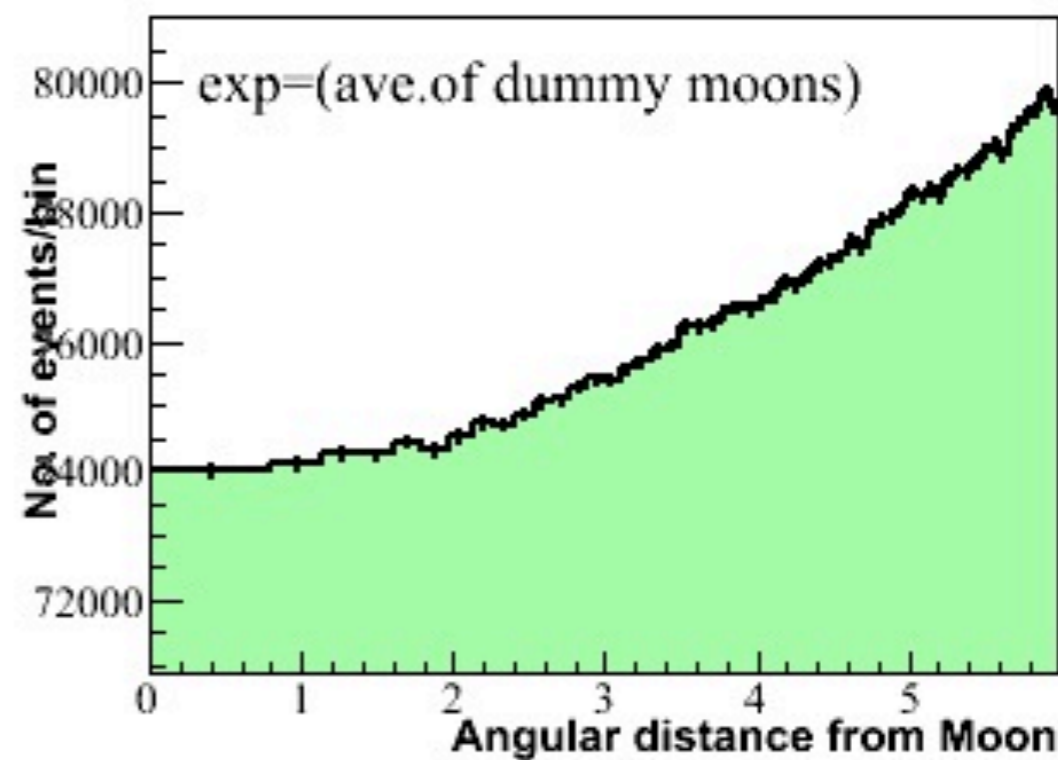
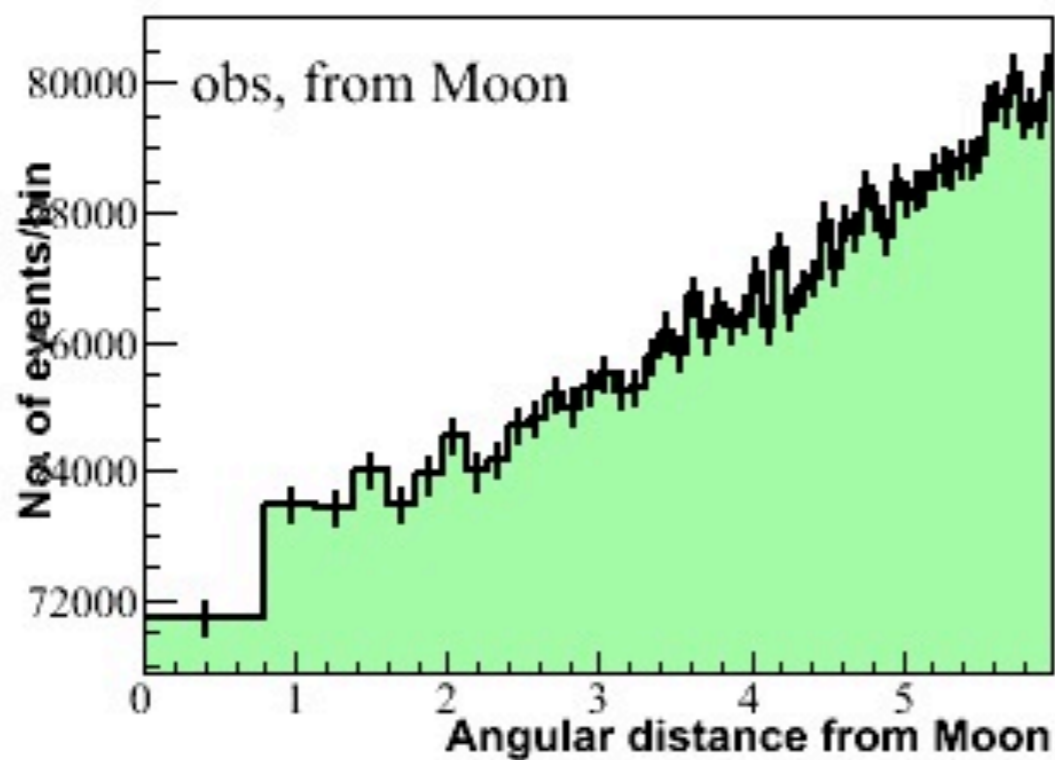
- Observe rate: 35k events/ sq°
 - 70.4k in each background bin
 - 7k events blocked by Moon
- Search bin contains 35% blocked events

$$S = \sqrt{2} \left\{ N_{\text{on}} \ln \left[\frac{1 + \alpha}{\alpha} \left(\frac{N_{\text{on}}}{N_{\text{on}} + N_{\text{off}}} \right) \right] + N_{\text{off}} \ln \left[(1 + \alpha) \left(\frac{N_{\text{off}}}{N_{\text{on}} + N_{\text{off}}} \right) \right] \right\}^{1/2}$$



Expect 2500 event deficit:
 8.9σ





observed: 7.173×10^4 events

expected: 7.4×10^4 events

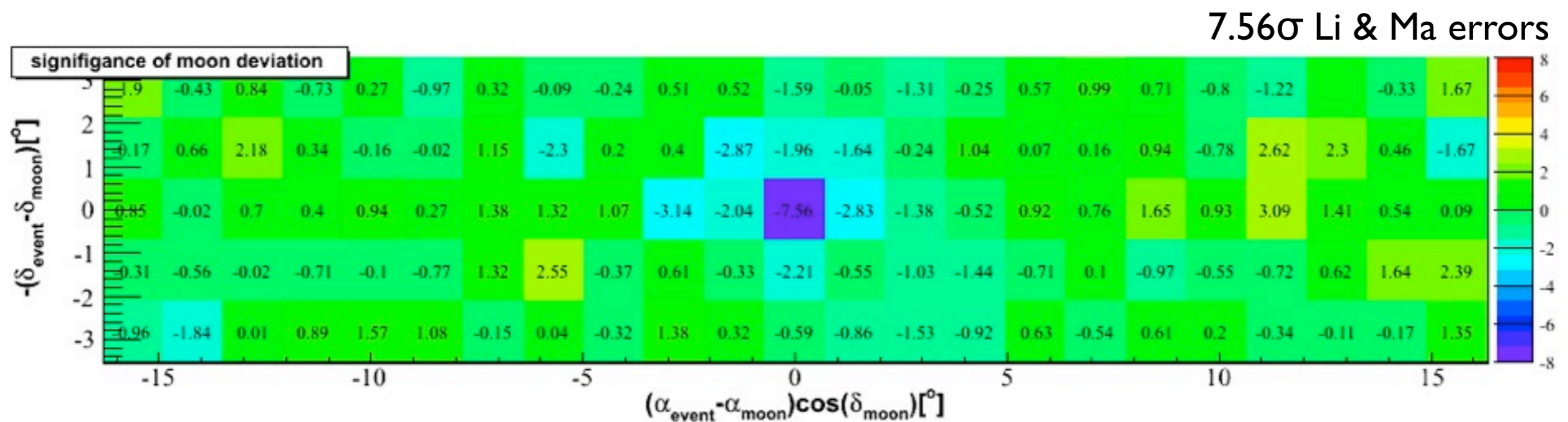
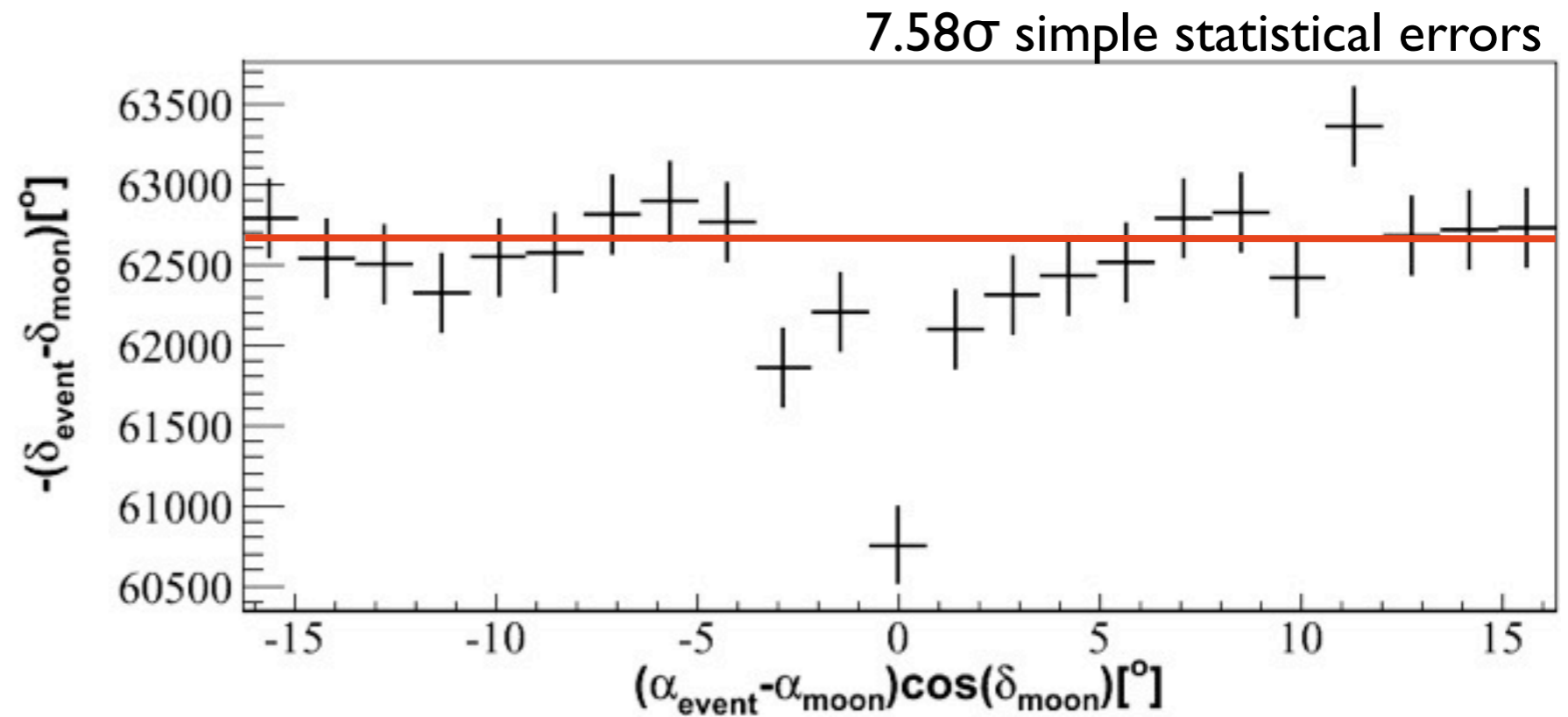
deficit: -2262 events

error: 285 events

significance: -7.9σ

Once events are reconstructed, this method is fast

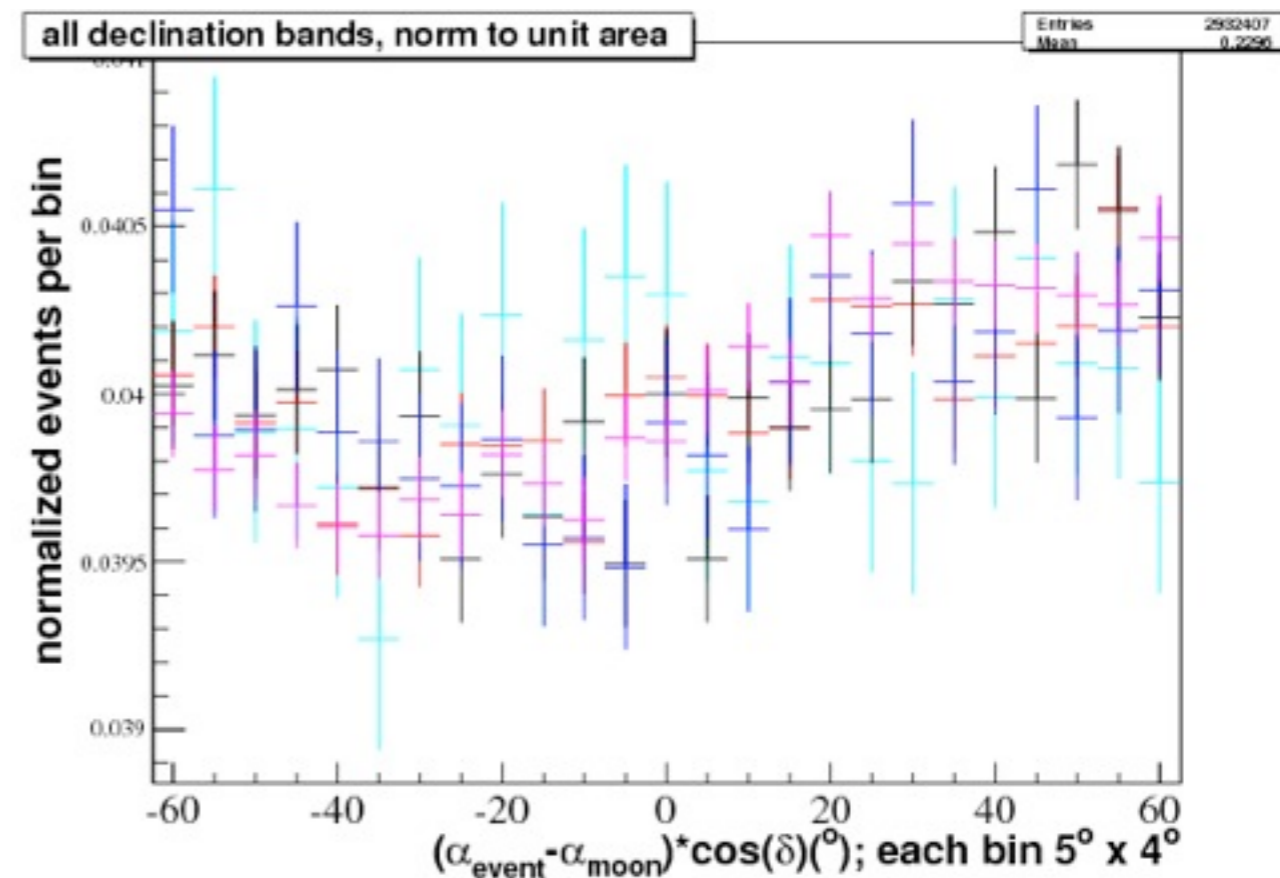
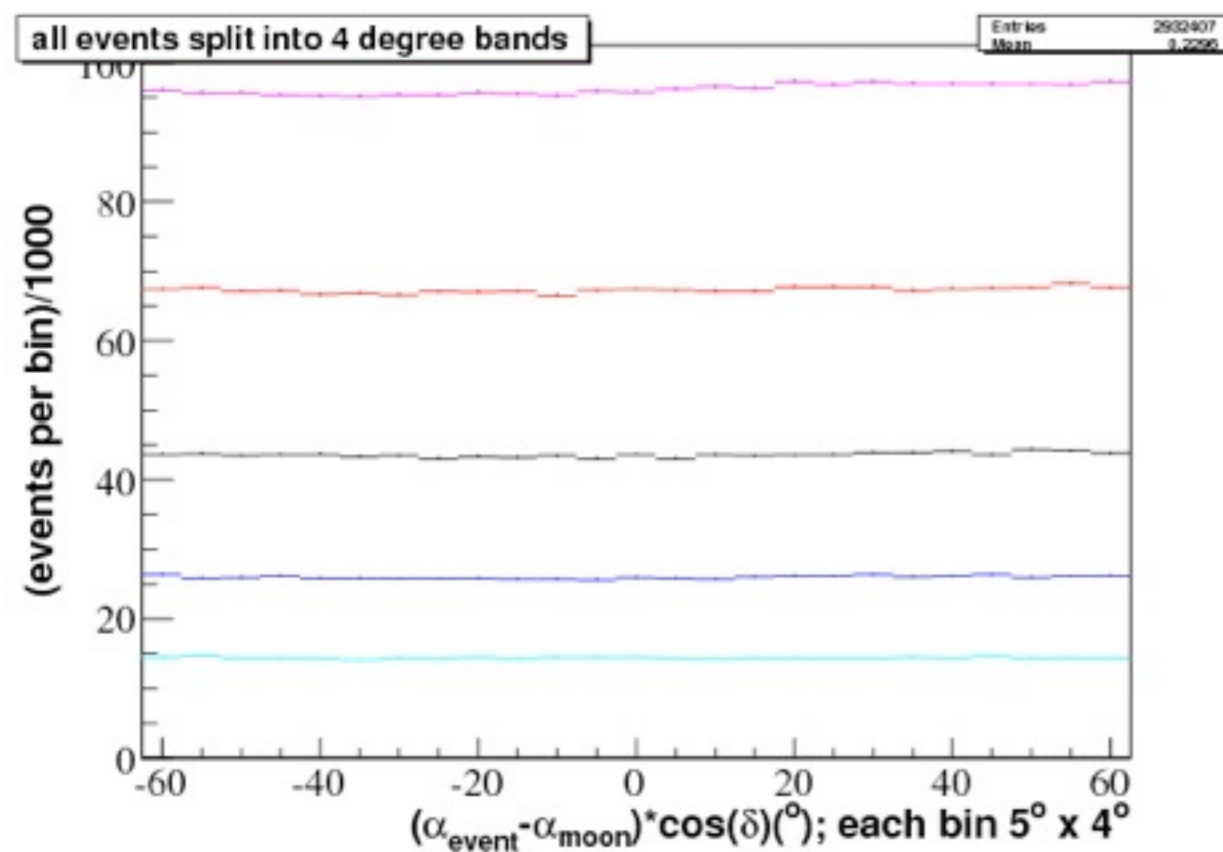
16



Alternate Binned Method

17

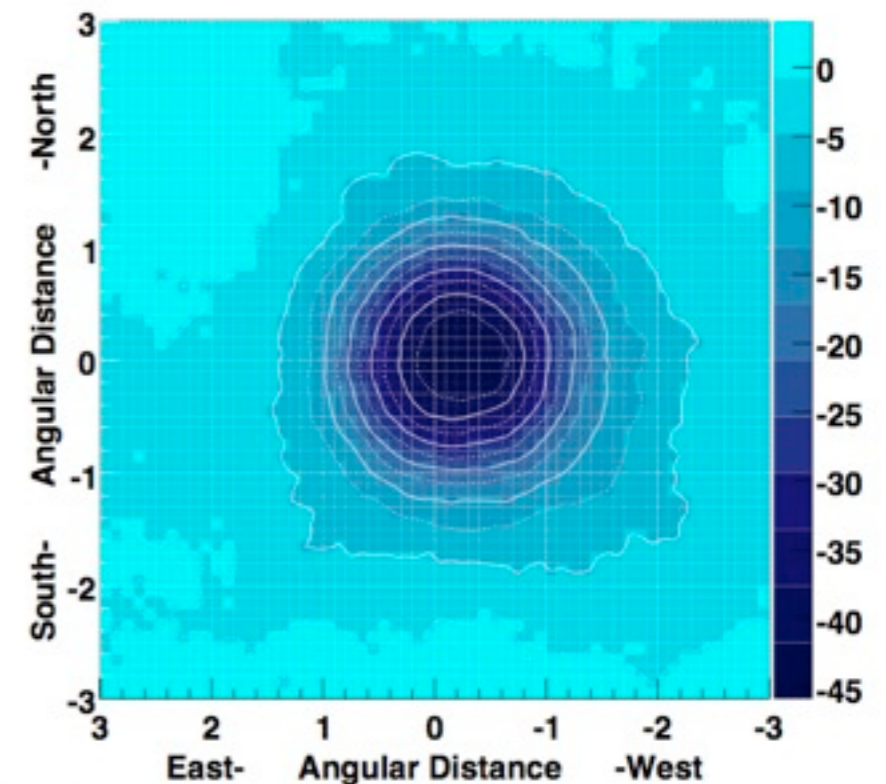
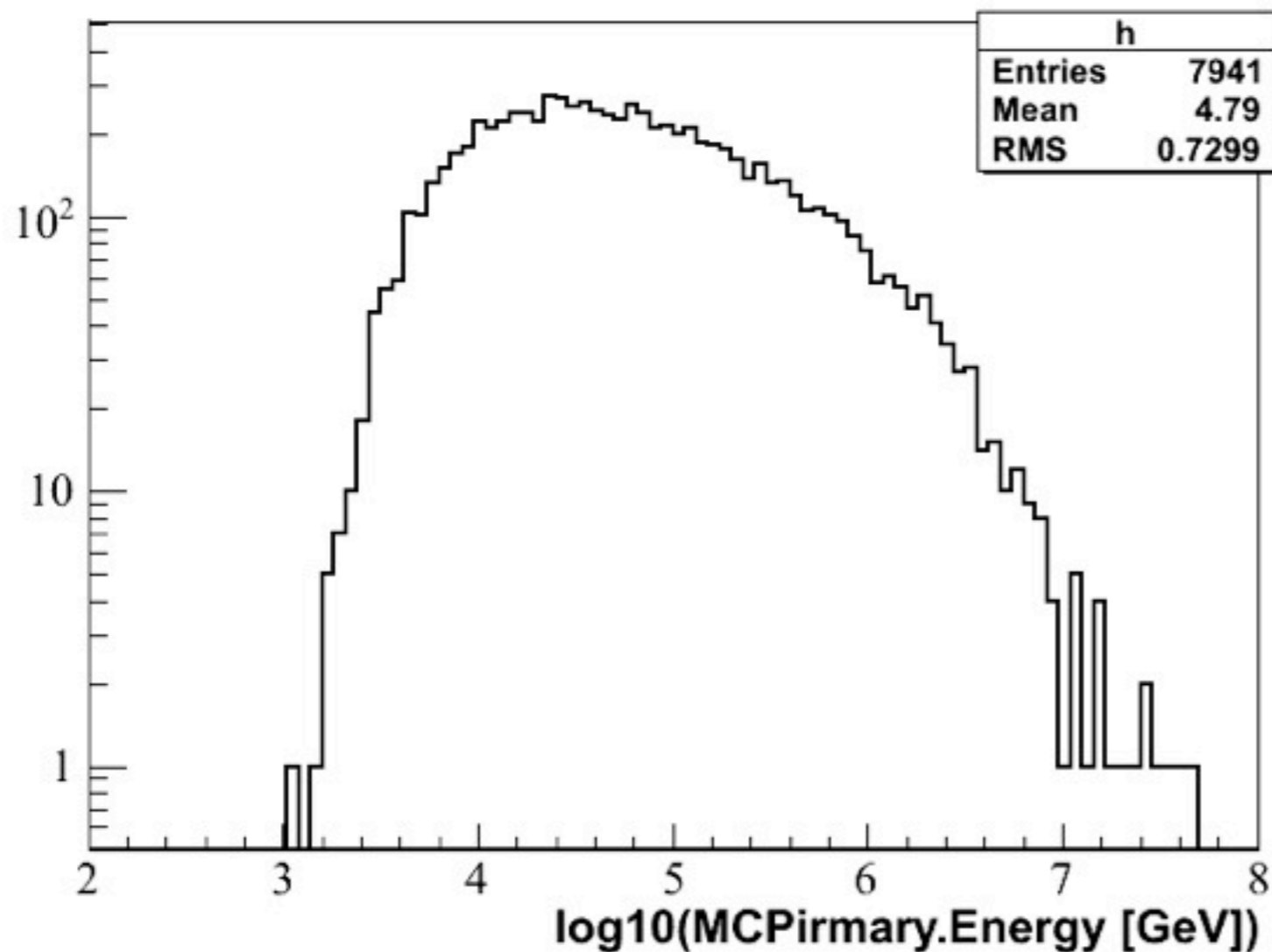
- Consider several declination bands:
- Use off-Moon bands to correct Moon band RA structure
- This was tried on IC22



It didn't work well enough with IC22,
and with IC40 a simpler binned analysis was good enough

Does Geomagnetic field matter?₁₈

- filter level cuts, zenith $> 50^\circ$



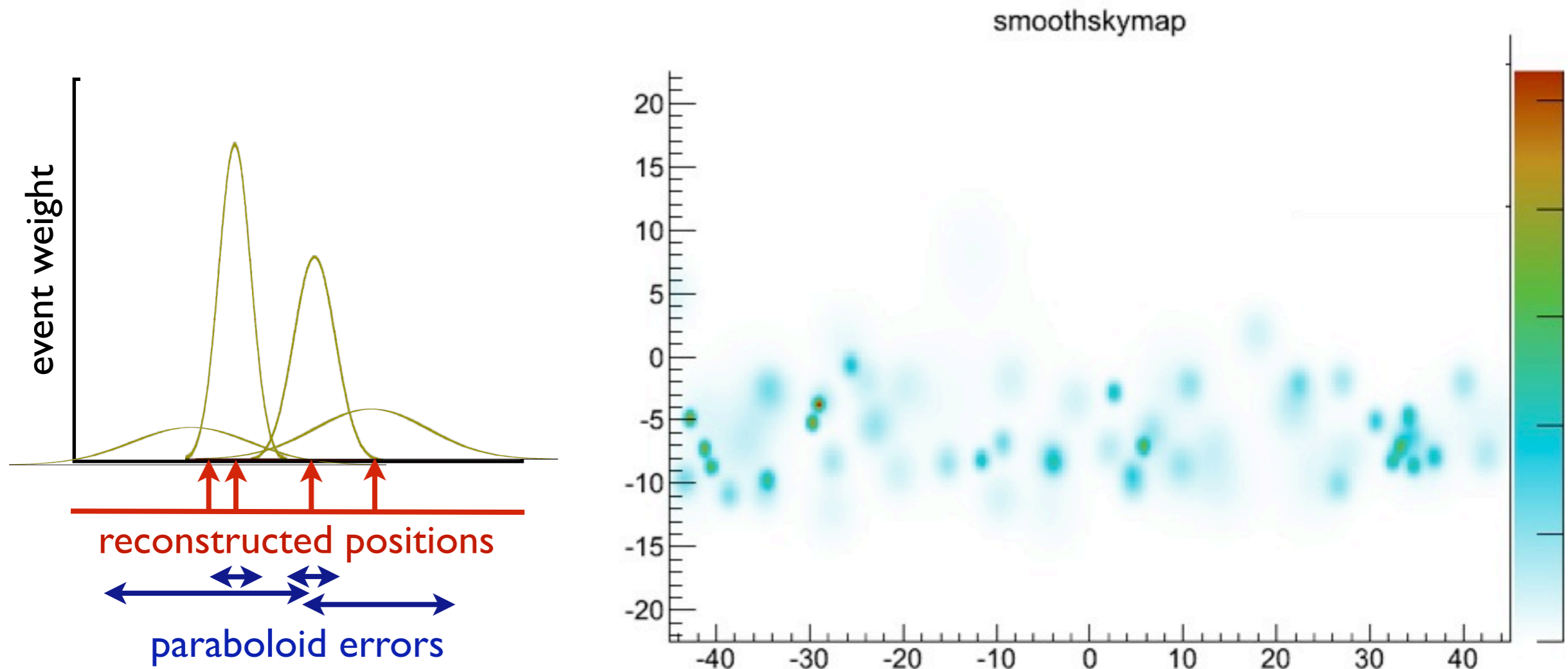
Shift from magnetic fields is negligible
Tibet Air Shower Array
[arXiv:0810.3757v1](https://arxiv.org/abs/0810.3757v1) [astro-ph]
I-40 TeV

→ shift is also negligible in this analysis

Approach II: Unbinned skymap

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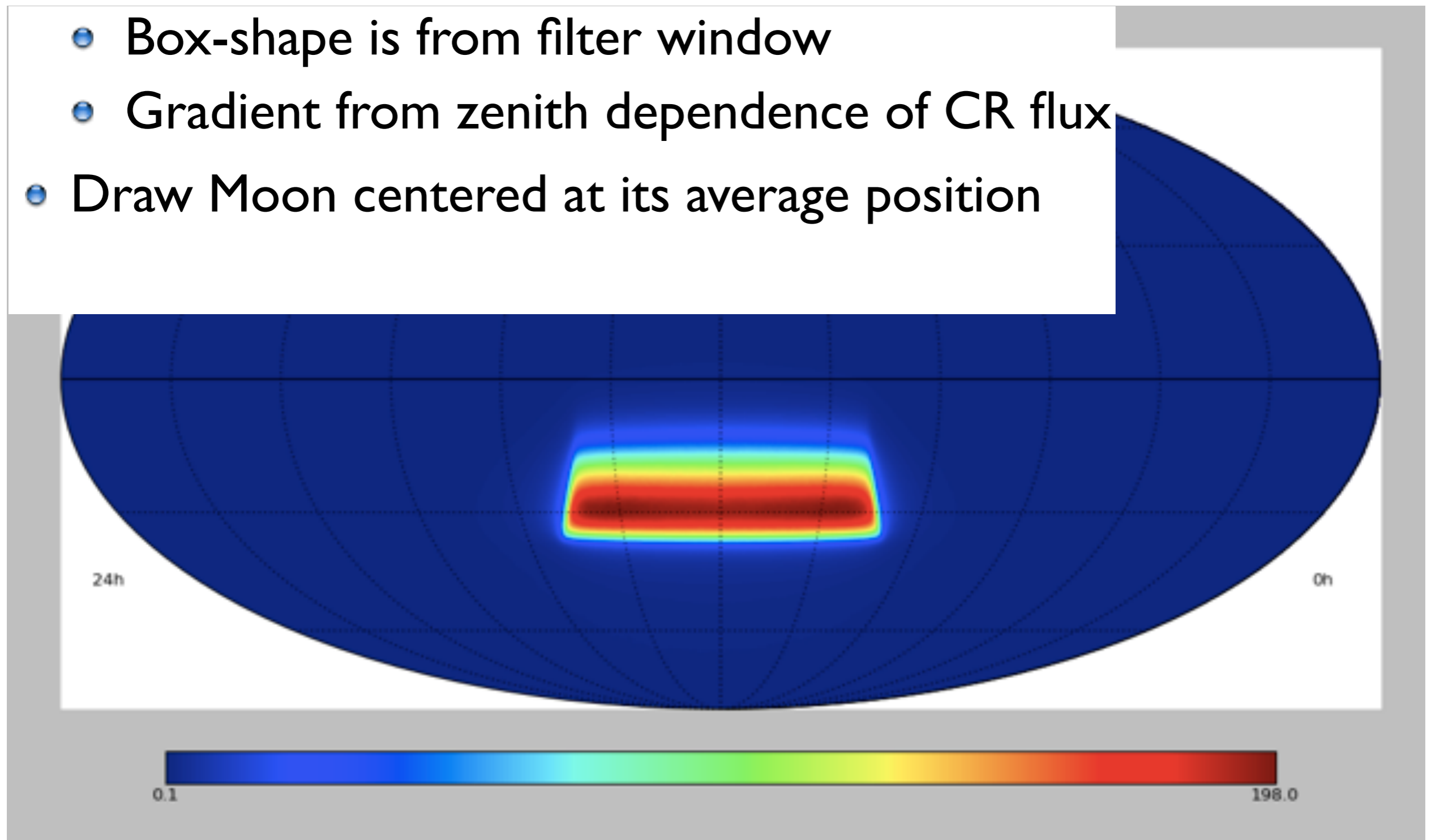
Smear each event by its paraboloid error
Map the total weighted event sum



Unbinned Skymap

20

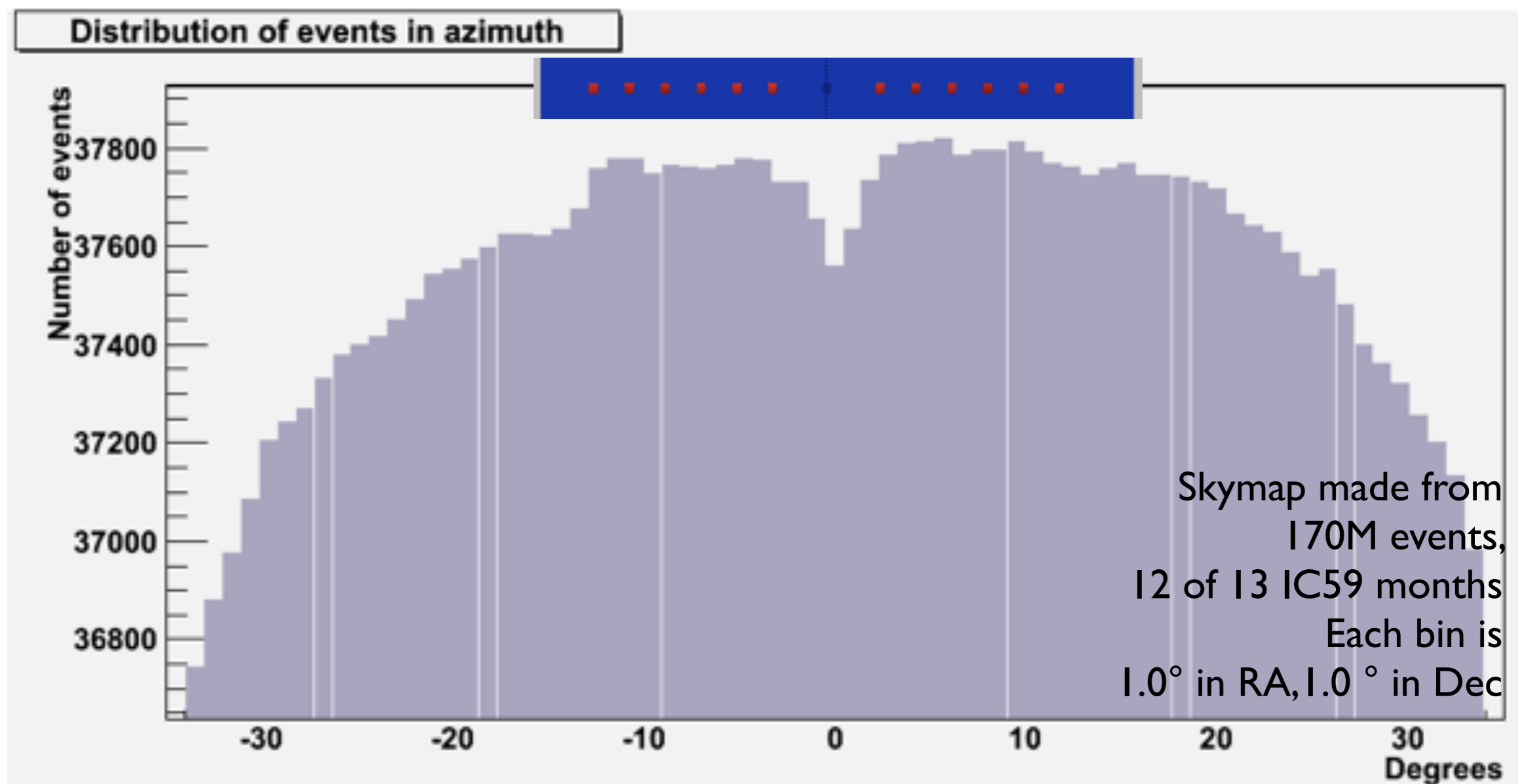
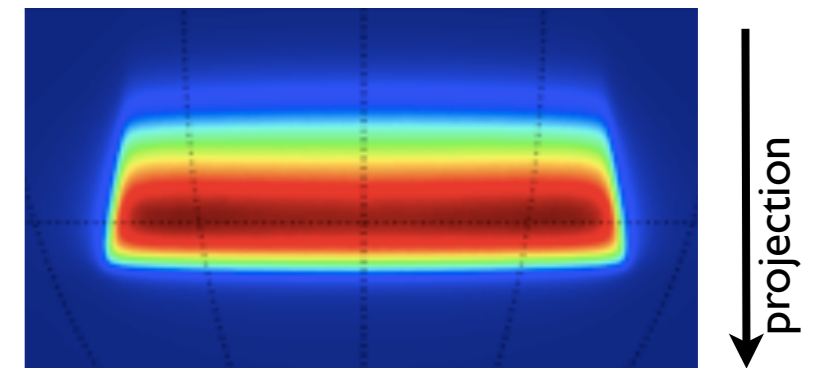
- Healpix: program for skymaps-- uses equal-area bins
- Box-shape is from filter window
- Gradient from zenith dependence of CR flux
- Draw Moon centered at its average position



Work in Progress:

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- Significance for IC59 skymap:
 - try dummy-moon approach
 - Assumes that RA distribution is flat:



Most-of-IC59 skymap

22

Skymap made from
170M events,
12 of 13 IC59 months



3° 2° 2°



17°

7.7°



Each bin:
0.01° in RA
0.01° in Dec